



# 3ware<sup>®</sup> Serial ATA RAID Controller

Command Line Interface

**Supports the 9000 Series**

**(9500S, 9550SX, 9590SE, 9650SE)**

PN: 720-0145-00

October 2006

**CLI Guide**

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# About this CLI Guide

*3ware Serial ATA Controller CLI Guide* provides instructions for configuring and maintaining your 3ware controller using 3ware's command line interface (CLI).

**Table 1: Sections in this CLI Guide**

Chapter	Description
1. Introduction to 3ware Command Line Interface	Installation, features, concepts
2. CLI Syntax Reference	Describes individual commands using the primary syntax

There are often multiple ways to accomplish the same configuration and maintenance tasks for your 3ware controller. While this manual includes instructions for performing tasks using the command line interface, you can also use the following applications:

- 3ware BIOS Manager
- 3DM<sup>®</sup>2 (3ware Disk Manager)

For details, see the user guide or the 3ware HTML Bookshelf.

# 1

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## Introduction to the 3ware Command Line Interface

The 3ware SATA RAID Controller Command Line Interface (CLI) for Linux, Windows, and FreeBSD is provided to manage 7000, 8000, and 9000-series 3ware ATA and Serial ATA RAID controllers. Multiple 3ware RAID controllers can be managed using the CLI via a command line or script.



**Note:** Some CLI commands are supported only for particular models of 3ware RAID controllers. Wherever possible, commands are labeled to indicate when they are supported for only a subset of controllers. For example, commands that apply only to 3ware 9000 series controllers are labeled as such and are not supported for 3ware 7000/8000 controllers. Within the 9000 series, some commands apply to only to models 9550SX, 9590SE, and 9650SE and not to 9500S, and are so labeled. A few commands apply only to models 9500S, and are labeled as such.



### Important!

For all of the functions of the 3ware CLI to work properly, you must have the proper CLI, firmware, and driver versions installed. Check <http://www.3ware.com> for the latest versions and upgrade instructions.

This chapter includes the following sections:

- “Features of the CLI” on page 2
- “Installing the 3ware CLI” on page 4
- “Working with 3ware CLI” on page 6
- “Understanding RAID Levels and Concepts” on page 9

## Features of the CLI

3ware CLI is a command line interface for managing 3ware RAID Controllers. It provides controller, logical unit, enclosure, and BBU (Battery Backup Unit) management. It can be used in both interactive and batch mode, providing higher level API (application programming interface) functionalities.



You can use the CLI to view unit status and version information and perform maintenance functions such as adding or removing drives. 3ware CLI also includes advanced features for creating and deleting RAID units online.

For a summary of what you can do using the CLI, see “Common Tasks Mapped to CLI Commands” on page 19.

## Supported Operating Systems

The 3ware CLI is supported under the following operating systems:

- **Windows®.** Windows 2000, Windows XP, and Windows Server 2003, both 32-bit and 64-bit.
- **Linux®.** Redhat, SuSE, both 32-bit and 64-bit.
- **FreeBSD®,** both 32-bit and 64-bit.

For specific versions of Linux and FreeBSD that are supported for the 3ware CLI, see the Release Notes.

## Terminology

This document uses the following terminology:

**Logical Units.** Usually shortened to “units.” These are block devices presented to the operating system. A logical unit can be a one-tier, two-tier, or three-tier arrangement. JBOD, Spare, and Single logical units are examples of one-tier units. RAID 1 and RAID 5 are examples of two-tier units and as such will have sub-units. RAID 10 and RAID 50 are examples of three-tier units and as such will have sub-sub-units.

**Port.** A controller has one or many ports (typically 4, 8, 12, 16). Each port can be attached to a single disk drive. On a controller such as the 9590SE-4ME, with a multilane serial port connector, one connector supports four ports.

For additional information about 3ware controller concepts and terminology, see the user guide that came with your 3ware RAID controller or the user guide portions of the 3ware HTML Bookshelf.

## Installing the 3ware CLI



### Warning!

If you are using 3DM, as opposed to 3DM2, AMCC does not recommend installing both 3DM and CLI on the same system. Conflicts may occur. For example, if both are installed, alarms will be captured only by 3DM. You should use either CLI or 3DM to manage your 3ware RAID controllers.

This is not an issue for 3DM2. It can be installed with CLI.

(3DM was an earlier version of the software, which worked with 7/8000 model 3ware controllers. 3DM 2 works with the 9000-series.)

## Installing the 3ware CLI on Windows

3ware CLI can be installed or run directly from the 3ware software CD, or the latest version can be downloaded from the 3ware web site, <http://www.3ware.com>. Online manual pages are also available in nroff and html formats. These are located in `/packages/cli/tw_cli.8.html` or `tw_cli.8.nroff`.

### To install 3ware CLI on Windows

- Copy the file `tw_cli.exe` to the directory from which you want to run the program.

CLI is located on the 3ware CD in the directory `\packages\cli\windows`



**Note:** CLI comes in both 32-bit and 64-bit versions. Be sure to copy the correct version for the version of the operating system you are using.

### Permissions Required to Run CLI

To run CLI, you can be logged onto Windows with one of the following sets of permissions:

- Administrator
- User with administrator rights
- Domain administrator
- Domain user with Domain Admin or Administrator membership

Without the correct privileges, CLI will prompt and then exit when the application is executed.

If you are uncertain whether you have the correct permissions, contact your network administrator.

**To start CLI, do one of the following:**

- Start the 3ware CD and at the 3ware Escalade menu, click **Run CLI**.
- Or, open a console window, change to the directory where `tw_cli` is located, and at the command prompt, enter  
`tw_cli`
- OR, double-click the CLI icon in a folder.

The CLI prompt is displayed in a DOS console window.

## Installing the 3ware CLI on Linux and FreeBSD

3ware CLI can be installed or run directly from the 3ware software CD, or the latest version can be downloaded from the 3ware web site, <http://www.3ware.com>.

To install the 3ware CLI, copy `tw_cli` to the directory from which you want to run the program. CLI is located on the 3ware CD in `/packages/cli/freebsd` or `/packages/cli/linux`.

Online manual pages are also available in nroff and html formats. These are located in `/packages/cli/tw_cli.8.html` or `tw_cli.8.nroff`.

You will need to be root or have root privileges to install the CLI to `/usr/sbin` and to run the CLI.

Filename: `tw_cli`

To install the CLI to a different location, change `/usr/sbin/` to the desired location.



**Notes:**

The installation location needs to be in the environment path for root to execute the CLI without using complete paths (i.e., if installed to `/usr/sbin/`, you can type `tw_cli` on the command line, otherwise you will have to type the complete path:

```
/home/user/tw_cli
```

The 3ware CLI comes in both 32-bit and 64-bit versions. Be sure to copy the correct version for the version of the operating system you are using.

## Working with 3ware CLI

You can work with the 3ware CLI in different ways:

- Interactively, entering commands at the main prompt
- As a series of single commands
- By creating a script—an input file with multiple commands

The next few topics shows examples of these different methods.

- “Using the command interface interactively” on page 6
- “Using a single command with output” on page 7
- “Using an input file to execute a script” on page 7
- “Outputting the CLI to a Text File” on page 8

Examples shown in the CLI Syntax Reference chapter reflect the interactive method.

## Using the command interface interactively

You can use 3ware CLI interactively, entering commands at the main prompt and observing the results on the screen.

### To use the CLI interactively

- 1 Enter the following command:

```
# tw_cli
```

The main prompt is displayed, indicating that the program is awaiting a command.

```
//localhost>
```

- 2 At the CLI prompt, you can enter commands to show or act on 3ware controllers, units, and drives.

For example,

```
//localhost> show
```

displays all controllers in the system and shows details about them, like this:

Ctl	Model	Ports	Drives	Units	NotOpt	RRate	VRate	BBU
c0	9650SE-4	4	4	1	0	3	5	TESTING
c1	7500-12	12	8	3	1	2	-	-

## Using a single command with output

You can use 3ware CLI with line arguments, processing a single command at a time. To do so, simply enter the command and the arguments.

Single commands can be useful when you want to perform a task such as redirecting the output of the command to a file. It also allows you to use the command line history to eliminate some typing.

### Syntax

```
tw_cli <command_line_arguments>
```

### Example

```
tw_cli /c0 show diag > /tmp/3w_diag.out
```

## Using an input file to execute a script

You can operate 3ware CLI scripts by executing a file. The file is a text file containing a list of CLI commands which you have entered in advance. Each command must be on a separate line.

### Syntax

```
tw_cli -f <filename>
```

Where <filename> is the name of the text file you want to execute.

### Example

```
tw_cli -f clicommand.txt
```

This example executes the file `clicommand.txt`, and runs the CLI commands included in that file.

### Scripting example

Following is a scripting example using a text file called `config_unit.txt`, containing three commands. This example sets up a 12-port controller with two units: one with the first 2 drives mirrored, and another with the remaining drives in a RAID 5 array. It then prints the configurations for verification. The commands included in the script file are:

```
/c0 add type=raid1 disk=0-1  
/c0 add type=raid5 disk=2-11  
/c0 show
```

To run the script, enter:

```
tw_cli -f config_unit.txt
```

## Outputting the CLI to a Text File

You can have the output of the 3ware CLI, including errors, sent to a text file by adding `2>&1` to the end of the line. This could be useful, for example, if you want to email the output to AMCC Technical Support.

### Examples

```
tw_cli /c2/p0 show >> controller2port0info.txt 2>&1
or
tw_cli /c0 show diag >> Logfile.txt 2>&1
```

## Conventions

The following conventions are used through this guide:

- In text, `monospace` font is used for code and for things you type.
- In descriptions and explanations of commands, a bold font indicates the name of commands and parameters, for example, **/c0/p0 show all**.
- In commands, an italic font indicates items that are variable, but that you must specify, such as a controller ID, or a unit ID, for example, **/c0/p0 show *attribute***, and **/cx/px show all**
- In commands, brackets around an item indicates that it is optional.
- In commands, ellipses (...) indicate that more than one parameter at a time can be included, for example, **/c0/p0 show *attribute* [*attribute ...*]**, or that there is a range between two values from which you can pick a value, for example, **/cx set *carvesize*=[1024...2048]**.
- In commands, a vertical bar (|) indicates an 'or' situation where the user has a choice between more than one attribute, but only one can be specified.

**Example:** In the command to rescan all ports and reconstitute all units, the syntax appears as **/cx rescan [*noscan*]**. The brackets [ ] indicate that you may omit the *noscan* parameter, so that the operation will be reported to the operating system.

# Understanding RAID Levels and Concepts

3ware RAID controllers use RAID (Redundant Array of Inexpensive Disks) to increase your storage system's performance and provide fault tolerance (protection against data loss).

This section organizes information about RAID concepts and configuration levels into the following topics:

- “RAID Concepts” on page 1
- “Available RAID Configurations” on page 1
- “Determining What RAID Level to Use” on page 1

## RAID Concepts

The following concepts are important to understand when working with a RAID controller:

- **Arrays and Units.** In the storage industry, the term “array” is used to describe two or more disk drives that appear to the operating system as a single unit. When working with a 3ware RAID controller, “unit” is the term used to refer to an array of disks that is configured and managed through the 3ware software. Single-disk units can also be configured in the 3ware software.
- **Mirroring.** Mirrored arrays (RAID 1) write data to paired drives simultaneously. If one drive fails, the data is preserved on the paired drive. Mirroring provides data protection through redundancy. In addition, mirroring using a 3ware RAID controller provides improved performance because 3ware's TwinStor technology reads from both drives simultaneously.
- **Striping.** Striping across disks allows data to be written and accessed on more than one drive, at the same time. Striping combines each drive's capacity into one large volume. Striped disk arrays (RAID 0) achieve highest transfer rates and performance at the expense of fault tolerance.
- **Distributed Parity.** Parity works in combination with striping on RAID 5, RAID 6, and RAID 50. Parity information is written to each of the striped drives, in rotation. Should a failure occur, the data on the failed drive can be reconstructed from the data on the other drives.
- **Hot Swap.** The process of exchanging a drive without having to shut down the system. This is useful when you need to exchange a defective drive in a redundant array.

- **Array Roaming.** The process of removing a unit from a controller and putting it back later, either on the same controller, or a different one, and having it recognized as a unit. The disks may be attached to different ports than they were originally attached to, without harm to the data.

For definitions of other terms used throughout the documentation, see the “Glossary”.

## Available RAID Configurations

RAID is a method of combining several hard drives into one unit. It offers fault tolerance and higher throughput levels than a single hard drive or group of independent hard drives. RAID levels 0, 1, 10 and 5 are the most popular. AMCC's 3ware controllers support RAID 0, 1, 5, 6, 10, 50, JBOD and Single Disk. The information below provides a more in-depth explanation of the different RAID levels.

For how to configure RAID units, see “Configuring a New Unit” on page 96.

### RAID 0

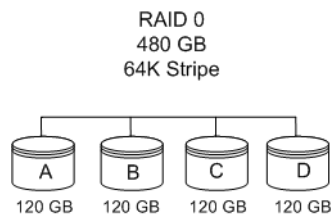
RAID 0 provides improved performance, but no fault tolerance. Since the data is striped across more than one disk, RAID 0 disk arrays achieve high transfer rates because they can read and write data on more than one drive simultaneously. The stripe size is configurable during unit creation. RAID 0 requires a minimum of two drives.

When drives are configured in a striped disk array (see Figure ?), large files are distributed across the multiple disks using RAID 0 techniques.

Striped disk arrays give exceptional performance, particularly for data intensive applications such as video editing, computer-aided design and geographical information systems.

RAID 0 arrays are not fault tolerant. The loss of any drive results in the loss of all the data in that array, and can even cause a system hang, depending on your operating system. RAID 0 arrays are not recommended for high availability systems unless additional precautions are taken to prevent system hangs and data loss.

**Figure 1. RAID 0 Configuration Example**





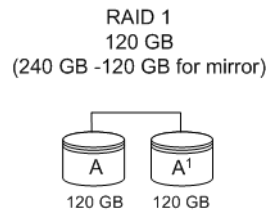
## RAID 1

RAID 1 provides fault tolerance and a speed advantage over non-RAID disks. RAID 1 is also known as a mirrored array. Mirroring is done on pairs of drives. Mirrored disk arrays write the same data to two different drives using RAID 1 algorithms (see Figure ?). This gives your system fault tolerance by preserving the data on one drive if the other drive fails. Fault tolerance is a basic requirement for critical systems like web and database servers.

3ware uses a patented technology, TwinStor®, on RAID 1 arrays for improved performance during sequential read operations. With TwinStor technology, read performance is twice the speed of a single drive during sequential read operation.

The adaptive algorithms in TwinStor technology boost performance by distinguishing between random and sequential read requests. For the sequential requests generated when accessing large files, both drives are used, with the heads simultaneously reading alternating sections of the file. For the smaller random transactions, the data is read from a single optimal drive head.

**Figure 2. RAID 1 Configuration Example**



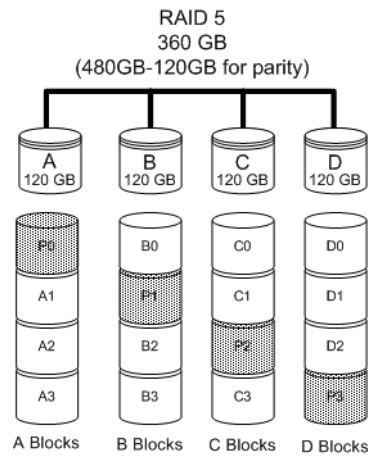
## RAID 5

RAID 5 provides performance, fault tolerance, high capacity, and storage efficiency. It requires a minimum of three drives and combines striping data with parity (exclusive OR) to restore data in case of a drive failure. Performance and efficiency increase as the number of drives in a unit increases.

Parity information is distributed across all of the drives in a unit rather than being concentrated on a single disk (see Figure ?). This avoids throughput loss due to contention for the parity drive.

RAID 5 is able to tolerate 1 drive failure in the unit.

**Figure 3. RAID 5 Configuration Example**



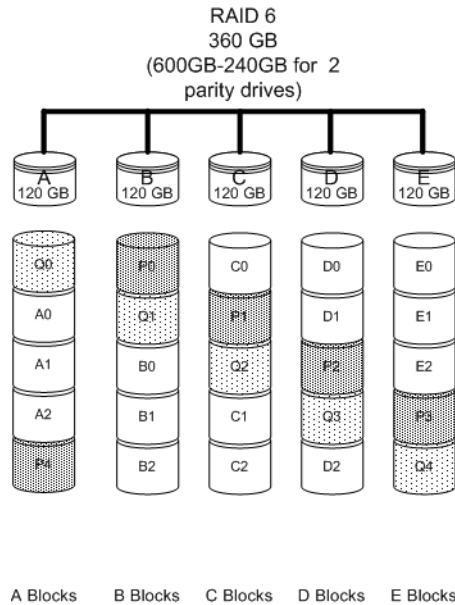
## RAID 6

RAID 6 requires a 3ware 9650SE RAID controller.

RAID 6 provides greater redundancy and fault tolerance than RAID 5. It is similar to RAID 5, but has two blocks of parity information (P+Q) distributed across all the drives of a unit, instead of the single block of RAID 5.

Due to the two parities, a RAID 6 unit can tolerate two hard drives failing simultaneously. This also means that a RAID 6 unit may be in two different states at the same time. For example, one sub-unit can be degraded, while another may be rebuilding, or one sub-unit may be initializing, while another is verifying.

RAID 6 requires a minimum of five drives. Performance and storage efficiency also increase as the number of drives increase.

**Figure 4. RAID 6 Configuration Example**

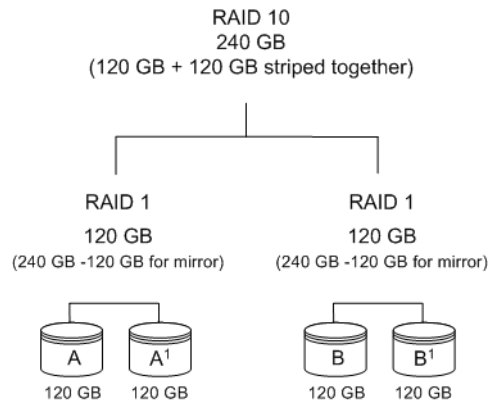
## RAID 10

RAID 10 is a combination of striped and mirrored arrays for fault tolerance and high performance.

When drives are configured as a striped mirrored array, the disks are configured using both RAID 0 and RAID 1 techniques, thus the name RAID 10 (see Figure ?). A minimum of four drives are required to use this technique. The first two drives are mirrored as a fault tolerant array using RAID 1. The third and fourth drives are mirrored as a second fault tolerant array using RAID 1. The two mirrored arrays are then grouped as a striped RAID 0 array using a two tier structure. Higher data transfer rates are achieved by leveraging TwinStor and striping the arrays.

In addition, RAID 10 arrays offer a higher degree of fault tolerance than RAID 1 and RAID 5, since the array can sustain multiple drive failures without data loss. For example, in a twelve-drive RAID 10 array, up to six drives can fail (half of each mirrored pair) and the array will continue to function. Please note that if both halves of a mirrored pair in the RAID 10 array fail, then all of the data will be lost.

**Figure 5. RAID 10 Configuration Example**



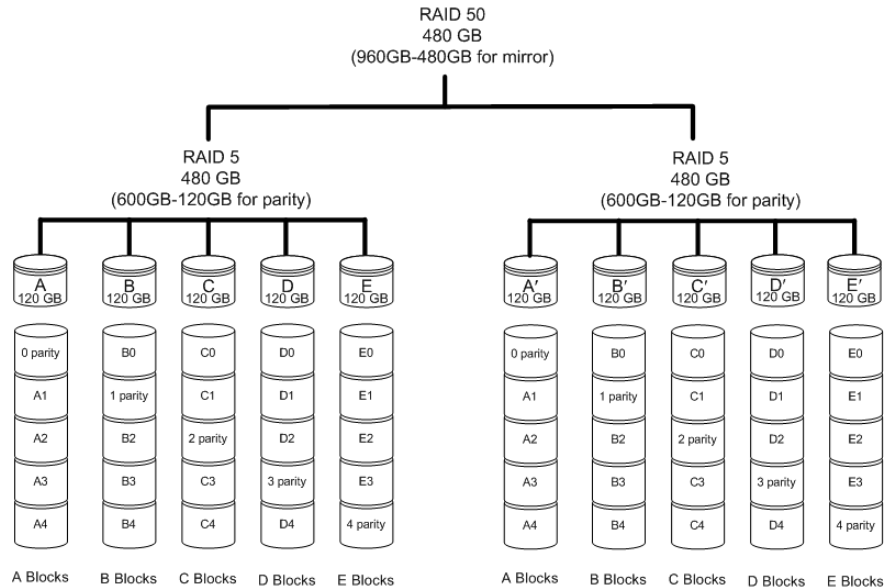
## RAID 50

RAID 50 is a combination of RAID 5 with RAID 0. This array type provides fault tolerance and high performance. RAID 50 requires a minimum of six drives.

Several combinations are available with RAID 50. For example, on a 12-port controller, you can have a grouping of 3, 4, or 6 drives. A grouping of 3 means that the RAID 5 arrays used have 3 disks each; four of these 3-drive RAID 5 arrays are striped together to form the 12-drive RAID 50 array. On a 16-port controller, you can have a grouping of 4 or 8 drives.

In addition, RAID 50 arrays offer a higher degree of fault tolerance than RAID 1 and RAID 5, since the array can sustain multiple drive failures without data loss. For example, in a twelve-drive RAID 50 array, up to one drive in each RAID 5 set can fail and the array will continue to function. Please note that if two or more drives in a RAID 5 set fail, then all of the data will be lost.

**Figure 6. RAID 50 Configuration Example**



## Single Disk

A single drive can be configured as a unit through 3ware software. (3BM, 3DM 2, or CLI). Like disks in other RAID configurations, single disks contain 3ware Disk Control Block (DCB) information and are seen by the OS as available units.

Single drives are not fault tolerant and therefore not recommended for high availability systems unless additional precautions are taken to prevent system hangs and data loss.

## JBOD

A JBOD (acronym for “Just a Bunch of Disks”) is an unconfigured disk attached to your 3ware RAID controller. JBOD configuration is no longer supported in the 3ware 9000 series. AMCC recommends that you use Single Disk as a replacement for JBOD, to take advantage of advanced features such as caching, OCE, and RLM.

JBOD units are not fault tolerant and therefore not recommended for high availability systems unless additional precautions are taken to prevent system hangs and data loss.

## Hot Spare

A hot spare is a single drive, available online, so that a redundant unit can be automatically rebuilt in case of drive failure.

## Determining What RAID Level to Use

Your choice of which type of RAID unit (array) to create will depend on your needs. You may wish to maximize speed of access, total amount of storage, or redundant protection of data. Each type of RAID unit offers a different blend of these characteristics.

The following table provides a brief summary of RAID type characteristics.

**Table 2: RAID Configuration Types**

RAID Type	Description
RAID 0	Provides performance, but no fault tolerance.
RAID 1	Provides fault tolerance and a read speed advantage over non-RAID disks.
RAID 5	This type of unit provides performance, fault tolerance, and high storage efficiency. RAID 5 units can tolerate one drive failing before losing data.
RAID 6	Provides very high fault tolerance with the ability to protect against two consecutive drive failures. Performance and efficiency increase with higher numbers of drives.
RAID 10	A combination of striped and mirrored units for fault tolerance and high performance.
RAID 50	A combination of RAID 5 and RAID 0. It provides high fault tolerance and performance.
Single Disk	Not a RAID type, but supported as a configuration. Provides for maximum disk capacity with no redundancy.

You can create one or more units, depending on the number of drives you have installed.

**Table 3: Possible Configurations Based on Number of Drives**

# Drives	Possible RAID Configurations
1	Single disk or hot spare
2	RAID 0 or RAID 1

**Table 3: Possible Configurations Based on Number of Drives**

# Drives	Possible RAID Configurations
3	RAID 0 RAID 1 with hot spare RAID 5
4	RAID 5 with hot spare RAID 10 Combination of RAID 0, RAID 1, single disk
5	RAID 6 RAID 5 with hot spare RAID 10 with hot spare Combination of RAID 0, RAID 1, hot spare, single disk
6 or more	RAID 6 RAID 6 with hot spare RAID 50 Combination of RAID 0, 1, 5, 6,10, hot spare, single disk

## Using Drive Capacity Efficiently

To make the most efficient use of drive capacity, it is advisable to use drives of the same capacity. This is because the capacity of each drive is limited to the capacity of the smallest drive in the unit.

The total array capacity is defined as follows:

**Table 4: Drive Capacity**

RAID Level	Capacity
Single Disk	Capacity of the drive
RAID 0	(number of drives) X (capacity of the smallest drive)
RAID 1	Capacity of the smallest drive
RAID 5	(number of drives - 1) X (capacity of the smallest drive) Storage efficiency increases with the number of disks: storage efficiency = (number of drives -1)/(number of drives)
RAID 6	(number of drives - 2) x (capacity of the smallest drive)
RAID 10	(number of drives / 2) X (capacity of smallest drive)

**Table 4: Drive Capacity**

RAID Level	Capacity
RAID 50	(number of drives - number of groups of drives) X (capacity of the smallest drive)

Through drive coercion, the capacity used for each drive is rounded down so that drives from differing manufacturers are more likely to be able to be used as spares for each other. The capacity used for each drive is rounded down to the nearest GB for drives under 45 GB (45,000,000,000 bytes), and rounded down to the nearest 5 GB for drives over 45 GB. For example, a 44.3 GB drive will be rounded down to 44 GB, and a 123 GB drive will be rounded down to 120 GB. For more information, see the discussion of drive coercion under “Creating a Hot Spare” on page 108.

## Support for Over 2 Terabytes

Windows 2000, Windows XP (32-bit), Linux 2.4, and FreeBSD 4.x, do not currently recognize unit capacity in excess of 2 TB.

If the combined capacity of the drives to be connected to a unit exceeds 2 Terabytes (TB), you can enable auto-carving when you configure your units.

Auto-carving divides the available unit capacity into multiple chunks of 2 TB or smaller that can be addressed by the operating systems as separate volumes. The carve size is adjustable from 1024 MB to 2048 MB (default) prior to unit creation.

If a unit over 2 TB was created prior to enabling the auto-carve option, its capacity visible to the operating system will still be 2TB; no additional capacity will be registered. To change this, the unit has to be recreated.

For more information, see “Using Auto-Carving for Multi LUN Support” on page 91.



# CLI Syntax Reference

This chapter provides detailed information about using the command syntax for the 3ware CLI.

Throughout this chapter the examples reflect the interactive method of executing 3ware CLI.

## Common Tasks Mapped to CLI Commands

The table below lists many of the tasks people use to manage their RAID controllers and units, and lists the primary CLI command associated with those tasks.

**Table 5: Common Tasks Mapped to CLI Commands**

Task	CLI Command	Page
<b>Controller Configuration Tasks</b>		
View information about a controller	/cx show	30
View controller policies	/cx show [attribute] [attribute]	31
Set policies for a controller		
<ul style="list-style-type: none"> <li>• Export JBODs</li> </ul>	/cx set exportjbod	55
<ul style="list-style-type: none"> <li>• Modify staggered spinup</li> </ul>	/cx set stagger and /cx set spinup	56
<ul style="list-style-type: none"> <li>• Disable write cache on unit degrade</li> </ul>	/cx set ondegrade	55
<ul style="list-style-type: none"> <li>• Enable/disable autocarving</li> </ul>	/cx set autocarve	56
<ul style="list-style-type: none"> <li>• Enable/disable autorebuild</li> </ul>	/cx set autorebuild	56
<ul style="list-style-type: none"> <li>• Set the autocarve volume size</li> </ul>	/cx set carvesize	56
<b>Unit Configuration Tasks</b>		
Create a new unit	/cx add	40
Create a hot spare	/cx add	40

**Table 5: Common Tasks Mapped to CLI Commands**

<b>Task</b>	<b>CLI Command</b>	<b>Page</b>
Enable/disable unit write cache	/cx/ux set cache	68
Set the queue policy	/cx/ux set qpolicy	70
Set the storsave profile	/cx/ux set storsave	70
<b>Unit Configuration Changes</b>		
Change RAID level	/cx/ux migrate	72
Change stripe size	/cx/ux migrate	72
Expand unit capacity	/cx/ux migrate	72
Delete a unit	/cx/ux del	66
Remove a unit (export)	/cx/ux remove	65
Name a unit	/cx/ux set name	70
<b>Controller Maintenance Tasks</b>		
Update controller with new firmware	/cx update	44
Add a time slot to a rebuild schedule	/cx add rebuild	50
Add a time slot to a verify schedule	/cx add verify	51
Add a time slot to a selftest schedule	/cx add selftest	52
Enable/disable the rebuild/migrate schedule and set the task rate	/cx set rebuild	53
Enable/disable the verify schedule and set the task rate	/cx set verify	54
Enable/disable the selftest schedule	/cx set selftest	54
View Alarms	/cx show alarms	45
<b>Unit Maintenance Tasks</b>		
Start a rebuild	/cx/ux start rebuild	66
Start a verify	/cx/ux start verify	67
Pause/resume rebuild	/cx/ux pause rebuild and /cx/ux resume rebuild	67
Stop verify	/cx/ux stop verify	68

**Table 5: Common Tasks Mapped to CLI Commands**

<b>Task</b>	<b>CLI Command</b>	<b>Page</b>
Enable/disable autoverify	/cx/ux set autoverify	68
Identify all drives that make up a unit by blinking associated LEDs	/cx/ux set identify	64
<b>Port Tasks</b>		
Locate drive by blinking an LED	/cx/px set identify	81
Check if LED is set to on or off	/cx/px show identify	78
View information for specific drive	/cx/px show	77
View the status of specific drive	/cx/px show status	78
<b>BBU Tasks</b>		
Check on charge and condition of battery	/cx/bbu/ show status	83
Start a test of the battery	/cx/bbu test [quiet]	86
<b>Enclosure Tasks</b>		
View information about an enclosure	/ex show	87
Locate a particular drive slot in an enclosure by blinking an LED	/ex/slotx set identify	90

## Syntax Overview

The command syntax uses the general form:

Object Command Attributes

**Objects** are shell commands, controllers, units, ports (drives), BBUs (battery backup units), and enclosures.

**Commands** can either select (show, get, present, read) attributes or alter (add, change, set, write) attributes.

**Attributes** are either Boolean Attributes or Name-Value Attributes.

- The value of a boolean attribute is deduced by presence or lack of—that is, the attribute is either specified, or not. For example, the command **show alarms** by default lists alarms with the most recent alarm first. If you include the attribute **reverse**, as in the command **show alarms reverse**, alarms are listed in reverse order.
- The value of name-value attributes are expressed in the format *attribute=value*.

**Example:** When adding (creating) a unit to the controller with the following command string,

```
/c1 add type=raid1 disk=0-1
```

`c1` is the object, `add` is the command, `type` (for type of array) is an attribute with `raid1` as the value of the attribute, and `disk` is another attribute with `0-1` as the value (ports 0 through 1).

Information about commands is organized by the object on which the commands act:

**Shell Object Commands.** Shell object commands set the focus or provide information (such as alarms, diagnostics, rebuild schedules, and so forth) about all controllers in the system. For details, see “Shell Object Commands” on page 23.

**Controller Object Commands.** Controller object commands provide information and perform actions related to a specific controller. For example, you use controller object commands for such tasks as seeing alarms specific to a controller, creating schedules during which background tasks are run, and setting policies for the controller. You also use the controller object command **/cx add type** to create RAID arrays. For details, see “Controller Object Commands” on page 29.

**Unit Object Commands.** Unit object commands provide information and perform actions related to a specific unit on a specific controller. For example, you use unit object commands for such tasks as seeing the rebuild, verify, or initialize status of a unit, starting, stopping, and resuming verifies, starting and stopping rebuilds, and setting policies for the unit. You also use the controller object command **/cx/ux migrate** to change the configuration of a RAID array. For details, see “Unit Object Commands” on page 59.

**Port Object Commands.** Port object commands provide information and perform actions related to a drive on a specific port. For example, you use port object commands for such tasks as seeing the status, model, or serial number of the drive. For details, see “Port Object Commands” on page 77.

**BBU Object Commands.** BBU object commands provide information and perform actions related to a Battery Backup Unit on a specific controller. For details, see “BBU Object Commands” on page 82.

**Enclosure Object Commands.** Enclosure object commands provide information and perform actions related to a particular enclosure. For example, you can use enclosure object commands to see information about an enclosure and its elements (slots, fan, and temperature sensor elements).

**Help Commands.** Help commands allow you to display help information for all commands and attributes. For details, see “Help Commands” on page 91.

## Shell Object Commands

Shell object commands are either applicable to all the controllers in the system (such as show, rescan, flush, commit), or redirect the focused object.

### Syntax

```
focus object
show [attribute [modifier]]
    ver
    alarms [reverse]
    diag
    rebuild
    verify
    selftest
rescan
flush
commit
update fw=filename_with_path [force]
```

### focus *Object*

The focus command is active in interactive mode only and is provided to reduce typing.

The focus command will set the specified object in focus and change the prompt to reflect this. This allows you to enter a command that applies to the focus, instead of having to type the entire object name each time.

For example, where normally you might type:

```
//hostname/c0/u0 show
```

if you set the focus to `//hostname/c0/u0`, the prompt changes to reflect that, and you only have to type `show`. The concept is similar to being in a particular location in a file system and requesting a listing of the current directory.

*object* can have the following forms:

`//hostname/cx/ux` specifies the fully qualified URI (Universal Resource Identifier) of an object on host `hostname`, controller `cx`, unit `ux`.

`//hostname` specifies the root of host `hostname`.  
`..` specifies one level up (the parent object).  
`/` specifies the root at the current focused hostname.  
`.object` specifies the next level of the object.  
`/c0/bbu` specifies a relative path with respect to the current focused hostname.

**Example:**

```
//localhost> focus /c0/u0
//localhost/c0/u0>

//localhost/c0/u0> focus..
//localhost/c0>

//localhost> focus u0
//localhost/c0/u0>

//localhost/c0> focus /
//localhost>
```

The `focus` command is available by default. You can disable `focus` by setting `TW_CLI_INPUT_STYLE` to **old**. (See “Return Code” on page 96.)

## show

This command shows a general summary of all detected controllers.

Note that the device drivers for the appropriate operating system should be loaded for the list to show all controllers. The intention is to provide a global view of the environment.

**Example:**

Typical output of the `Show` command looks like the following:

```
//localhost> show
Ctl  Model      Ports  Drives  Units  NotOpt  RRate  VRate  BBU
-----
c0  9590SE-4ME  4      4       1      0       2      5      -
```

The output above indicates that Controller 0 is a 9590SE model with 4 Ports, with 4 Drives detected (attached), total of 1 Unit, with no units in a NotOpt (Not Optimal) state, RRate (Rebuild Rate) of 2, VRate (Verify Rate) of 5, BBU of '-' (Not Applicable). Not Optimal refers to any state except OK and VERIFYING. Other states include VERIFY-PAUSED, INITIALIZING, INIT-PAUSED, REBUILDING, REBUILD-PAUSED, DEGRADED, MIGRATING, MIGRATE-PAUSED, RECOVERY, INOPERABLE, and UNKNOWN. RRate also applies to initializing, migrating, and recovery

background tasks. (Definitions of the unit statuses are available in the *3ware Serial ATA RAID Controller User Guide*.)

For a system with an enclosure unit that includes support for an EPCT (Enclosure Port Configuration Table), applicable firmware and software, and an appropriate controller (9550SX, 9590SE, or 9650SE), a global view of the environment also includes summary information about detected enclosures.

**Example:**

Typical output of the Show command for a system with an enclosure looks like the following:

```
//localhost> show
Ctl      Model          Ports   Drives  Units  NotOpt  RRate  VRate  BBU
-----
c0       9650SE-4LPML   4       2       1      0       4      4      -

Encl     Slots   Drives  Fans   TSUnits  Ctls
-----
e0       4       2       1     1        1
```

The output above shows the enclosure summary information with the name of the enclosure, the protocol used, the number of drive slots, the number of drives, the number of fans, the number of temperature sensors, and the number of controllers that are associated with the enclosure.

## show ver

This command will show the CLI and API version.

**Example:**

```
//localhost> show ver
CLI Version = 2.00.03.0xx
API Version = 2.01.00.xx
```

In the above example, “xx” stands for the actual version. See the Release Notes for details.

## show alarms [reverse]

This command shows the alarms or AEN messages of all controllers in the system. The default is to display the most recent message first. The **reverse** attribute displays the most recent message last.

## show diag

This command shows the diagnostic information of all controllers in the system.

## show rebuild

This command displays all rebuild schedules for the 9000 controllers in the system.

The rebuild rate is also applicable for initializing, migrating, and recovery background tasks.

**Example:**

```
//localhost> show rebuild
```

```
Rebuild Schedule for Controller /c0
```

```
=====
```

Slot	Day	Hour	Duration	Status
1	Sun	12:00am	24 hr(s)	disabled
2	Mon	12:00am	24 hr(s)	disabled
3	Tue	12:00am	24 hr(s)	disabled
4	Wed	12:00am	24 hr(s)	disabled
5	Thu	12:00am	24 hr(s)	disabled
6	Fri	12:00am	24 hr(s)	disabled
7	Sat	12:00am	24 hr(s)	disabled

```
-----
```

For additional information about rebuild schedules, see “/cx add rebuild=ddd:hh:duration” on page 50, and see the discussion of background tasks and schedules in *3ware Serial ATA RAID Controller User Guide*.



## show verify

This command displays all verify schedules for the 9000 controllers in the system.

**Example:**

```
//localhost> show verify
```

```
Verify Schedule for Controller /c0
```

```
=====
```

Slot	Day	Hour	Duration	Status
1	Sat	11:00pm	4 hr(s)	enabled
2	-	-		enabled
3	-	-		enabled
4	-	-		enabled
5	-	-		enabled
6	-	-		enabled
7	-	-		enabled

For additional information about verify schedules, see “/cx add verify=ddd:hh:duration” on page 51, and see the discussion of background tasks and schedules in *3ware Serial ATA RAID Controller User Guide*.

## show selftest

This command displays all selftest schedules for the 9000 controllers in the system.

**Example:**

```
//localhost> show selftest
```

```
Selftest Schedule for Controller /c0
```

```
=====
```

Slot	Day	Hour	UDMA	SMART
1	Sun	12:00am	enabled	enabled
2	Mon	12:00am	enabled	enabled
3	Tue	12:00am	enabled	enabled
4	Wed	12:00am	enabled	enabled
5	Thu	12:00am	enabled	enabled
6	Fri	12:00am	enabled	enabled
7	Sat	12:00am	enabled	enabled

For additional information about selftest schedules, see “/cx add selftest=ddd:hh” on page 52, and see the discussion of background tasks and schedules in *3ware Serial ATA RAID Controller User Guide*.

## flush

This command sends a flush command to all 3ware controllers in the system. For more information, see “/cx flush” on page 44.

## rescan

This command sends a rescan command to all 3ware controllers in the system. For more information, see “/cx rescan [noscan]” on page 43.

## commit

This command sends a commit command to all 3ware controllers in the system. For more information, see “/cx commit” on page 44.

## update fw=*filename\_with\_path* [force]

This command downloads the specified firmware image to the controllers that are compatible with it and iterates through all the controllers in the system, updating the firmware. For more information, see “/cx update fw=*filename\_with\_path* [force]” on page 44.

# Controller Object Commands

Controller object commands provide information and perform actions related to a specific controller, such as /c0. For example, you use controller object commands to see alarms specific to a controller, to create schedules for when background tasks are run, and to set policies for the controller. You also use the controller object command /cx add type to create RAID arrays.

## Syntax

```

/cx show
/cx show attribute [attribute ...] where attributes are:
    achip|alarms|allunitstatus|autocarve (9000 series)|
    autorebuild(9550SX, 9590SE, 9650SE)|bios|
    carvesize(9000 series)|ctlbus(9550SX, 9590SE, 9650SE)|
    diag|driver| drivestatus|exportjbod(9000 series)|
    firmware|memory|model|monitor|ondegrade(9500S series)
    |pcb|pchip|numdrives|numports|numunits|
    rebuild(9000 series)|selftest(9000 series)|serial|
    spinup|stagger|unitstatus|verify(9000 series)
/cx show all (where all means attributes and configurations)
/cx show diag
/cx show alarms [reverse]
/cx show rebuild (9000 series)
/cx show verify (9000 series)
/cx show selftest (9000 series)

/cx add type=<RaidType> disk=<p:-p..> [stripe=<Stripe>]
    [noscan][nocache][group=<3|4|5|6|7|8>]
    [autoverify][noqpolicy][ignorECC]
    [name=string](9000 series) RaidType={raid0,raid1,raid5,
    raid6(9650SE only),raid10,raid50,single,spare,JBOD
    (7000/8000 only)}[storsave=<protect|balance|perform>]
    (9550SX, 9590SE, 9650SE)
/cx add rebuild=ddd:hh:duration (9000 only)
/cx add verify=ddd:hh:duration (9000 only)
/cx add selftest=ddd:hh (9000 only)

/cx del rebuild=slot_id (9000 only)
/cx del verify=slot_id (9000 only)
/cx del selftest=slot_id (9000 only)

/cx set exportjbod=on|off (9000 only)
/cx set ondegrade=cacheoff|follow (9500S only)
/cx set spinup=nn (9000 only)
/cx set stagger=nn (9000 only)
/cx set autocarve=on|off (9000 only)
/cx set carvesize=[1024...2048] (9000 only)
/cx set rebuild=enable|disable|1..5 (9000 only)

```

```

/cx set autorebuild=on|off (9550SX, 9590SE, 9650SE)
/cx set autodetect=on|off disk=<p:-p>|all
/cx set verify=enable|disable|1..5 (9000 only)
/cx set selftest=enable|disable [task=UDMA|SMART](9000 only)

/cx flush
/cx update fw=filename_with_path [force] (9000 only)
/cx commit (Windows only. Also known as shutdown)
/cx start mediascan (7000/8000 only)
/cx stop mediascan (7000/8000 only)
/cx rescan [noscan] (Does not import non-JBOD on 7000/8000
models.

```

## /cx show

This command shows summary information on the specified controller /cx. This information is organized into a report containing two to three parts:

- A **Unit** summary listing all present units
- A **Port** summary section listing of all ports and disks attached to them.
- A **BBU** summary section listing, if a BBU is installed on the controller.

The **Unit** summary section lists all present unit and specifies their unit number, unit type (such as RAID 5), unit status (such as INITIALIZING), %R (percent completion of rebuilding), % V/I/M (percent completion of verifying, initializing, or migrating), stripe size, size (usable capacity) in gigabytes or terabytes, and the auto-verify policy status (on/off)

Possible unit statuses include OK, RECOVERY, INOPERABLE, UNKNOWN, DEGRADED, INITIALIZING, INIT-PAUSED, VERIFYING, VERIFY-PAUSED, REBUILDING, REBUILD-PAUSED, MIGRATING, and MIGRATE-PAUSED. Definitions of the unit statuses are available in the *3ware Serial ATA RAID Controller User Guide*.



**Note:** If an asterisk (\*) appears next to the status of a unit, there is an error on one of the drives in the unit. This feature provides a diagnostic capability for potential problem drives. The error may not be a repeated error, and may be caused by an ECC error, SMART failure, or a device error. Rescanning the controller will clear the drive error status if the condition no longer exists.

The **Port** summary section lists all present ports and specifies the port number, disk status, unit affiliation, size (in gigabytes) and blocks (512 bytes), and the serial number assigned by the disk vendor.

The **BBU** summary lists details about the BBU, if one is installed. It includes a few important attributes such as hours left (in which the current BBU can

backup the controller cache in the event of power loss), temperature, voltage, readiness, and so forth.

Additional attributes about controllers, units, ports and disks can be obtained by querying for them explicitly. For details, see the other show subcommands.

Typical output looks like:

```
//localhost> /c2 show
```

Unit	UnitType	Status	%RCmpl	%V/I/M	Stripe	Size(GB)	Cache	AVrfy
u0	RAID-5	OK	-	-	64K	596.004	ON	OFF
u1	RAID-0	OK	-	-	64K	298.002	ON	OFF
u2	SPARE	OK	-	-	-	149.042	-	OFF
u3	RAID-1	OK	-	-	-	149.001	ON	OFF

Port	Status	Unit	Size	Blocks	Serial
p0	OK	u0	149.05 GB	312581808	WD-WCANM1771318
p1	OK	u0	149.05 GB	312581808	WD-WCANM1757592
p2	OK	u0	149.05 GB	312581808	WD-WCANM1782201
p3	OK	u0	149.05 GB	312581808	WD-WCANM1753998
p4	OK	u2	149.05 GB	312581808	WD-WCANM1766952
p5	OK	u3	149.05 GB	312581808	WD-WCANM1882472
p6	OK	u0	149.05 GB	312581808	WD-WCANM1883862
p7	OK	u3	149.05 GB	312581808	WD-WCANM1778008
p8	OK	-	149.05 GB	312581808	WD-WCANM1770998
p9	NOT-PRESENT	-	-	-	-
p10	OK	u1	149.05 GB	312581808	WD-WCANM1869003
p11	OK	u1	149.05 GB	312581808	WD-WCANM1762464

Name	OnlineState	BBUReady	Status	Volt	Temp	Hours	LastCapTest
bbu	On	Yes	OK	OK	OK	241	22-Jun-2004

## *lcx show attribute [attribute ...]*

This command shows the current setting of the specified attributes on the specified controller. One or many attributes can be specified. Specifying an invalid attribute will terminate the loop. Possible attributes are: achip, allunitstatus, autocarve (9000 series), autorebuild (9550SX, 9590SE, and 9650SE only), bios, carvesize (9000 series), driver, drivestatus, exportjbod (9000 series), firmware, memory, model, monitor, numdrives, numports, numunits, ctlbus (9550SX, 9590SE, and 9650SE only), ondegrade (9500S), pcb, pchip, qpolicy, serial, spinup (9000 series), stagger (9000 series), and unitstatus.

**Example:** To see the driver and firmware installed on controller 0, enter the following:

```
//localhost> /c0 show driver firmware
/c0 Driver Version = 2.x
/c0 Firmware Version = FE9X 3.x
```

(In the sample output above, “x” will be replaced with the actual version number.)

## /cx show driver

This command reports the device driver version associated with controller /cx.

**Example:**

```
//localhost> /c0 show driver
/c0 Driver Version = 2.x
```

## /cx show model

This command reports the controller model of controller /cx.

**Example:**

```
//localhost> /c0 show model
/c0 Model = 9500-x
```

## /cx show firmware

This command reports the firmware version of controller /cx.

**Example:**

```
//localhost> /c0 show firmware
/c0 Firmware Version = FE9X 3.03.06.X03
```

## /cx show bios

This command reports the BIOS version of controller /cx.

**Example:**

```
//localhost> /c0 show bios
/c0 BIOS Version = BG9X 2.x
```

## /cx show monitor

This command reports the monitor (firmware boot-loader) version of controller /cx.

**Example:**

```
//localhost> /c0 show monitor
/c0 Monitor Version = BLDR 2.x
```

## /cx show serial

This command reports the serial number of the specified controller /cx.

**Example:**

```
//localhost> /c0 show serial  
/c0 Serial Number = F12705A3240009
```

## /cx show pcb

This command reports the PCB (Printed Circuit Board) version of the specified controller /cx.

**Example:**

```
//localhost> /c0 show pcb  
/c0 PCB Version = RevX
```

## /cx show pchip

This command reports the PCHIP (PCI Interface Chip) version of the specified controller /cx.

**Example:**

```
//localhost> /c0 show pchip  
/c0 PCHIP Version = 1.x
```

## /cx show achip

This command reports the ACHIP (ATA Interface Chip) version of the specified controller /cx.

**Example:**

```
//localhost> /c0 show achip  
/c0 ACHIP Version = 3.x
```

## /cx show numdrives

This command reports the number of drives currently managed by the specified controller /cx. This report does not include (logically) removed or exported drives.

On 9500S and earlier controllers, physically-removed disk(s) will still be counted. For a workaround, see “/cx/px show smart” on page 79.

**Example:**

```
//localhost> /c0 show numdrives  
/c0 Number of Drives = 5
```

## /cx show numports

This command reports the port capacity (number of physical ports) of the specified controller /cx.

**Example:**

```
//localhost> /c0 show numports
/c0 Number of Ports = 12
```

## /cx show numunits

This command reports the number of units currently managed by the specified controller /cx. This report does not include off-line units (or removed units).

**Example:**

```
//localhost> /c0 show numunits
/c0 Number of Units = 1
```

## /cx show ctlbus

This feature only applies to 9550SX, 9590SE, and 9650SE controllers.

This command reports the controller host bus type, bus speed, and bus width.

**Example:**

```
//localhost> /c0 show ctlbus
/c0 Controller Bus Type = PCI-X
/c0 Controller Bus Width = 64 bits
/c0 Controller Bus Speed = 133 Mhz
```

## /cx show exportjbod

This feature only applies to 9000 series controllers.

This command reports the current JBOD Export Policy: **on**, **off**, or **Not Supported**.

**Example:**

```
//localhost> /c0 show exportjbod
/c0 JBOD Export Policy = Not Supported.
//localhost> /c1 show exportjbod
/c1 JBOD Export Policy = on
```



## /cx show spinup

This feature only applies to 9000 series controllers.

This command reports the number of concurrent disks that will spin up when the system is powered on, after waiting for the number of seconds specified with the `set stagger` command.

**Example:**

```
//localhost> /c0 show spinup
/c0 Disk Spinup Policy = 1
```

## /cx show stagger

This feature only applies to 9000 series controllers.

This command reports the time delay between each group of spinups at the power on.

**Example:**

```
//localhost> /c0 show stagger
/c0 Spinup Stagger Time Policy (sec) = 2
```

## /cx show ondegrade

This feature only applies to 9500S controllers.

This command reports the cache policy for degraded units. If the ondegrade policy is “Follow Unit Policy,” a unit cache policy stays the same when the unit becomes degraded. If the ondegrade policy is off, a unit cache policy will be forced to “off” when the unit becomes degraded.

**Example:**

```
//localhost> /c0 show ondegrade
/c0 Cache on Degraded Policy = Follow Unit Policy
```

## /cx show autocarve

This feature only applies to 9000 series controllers.

This command reports the Auto-Carve policy. If the policy is **on**, all newly created or migrated units larger than the `carvesize` will be automatically carved into multiples of `carvesize` volumes plus one remainder volume. Each volume can be treated as an individual drive with its own file system. The default `carvesize` is 2TB. For more information see, “/cx show carvesize”, below.

For operating systems that support units larger than 2TB, there is no need to set the policy to **on** unless you want the operating system to have multiple smaller volumes.

If you use a 32-bit operating system, it is recommended that you keep the policy **on** unless you know that your operating system supports disks that are larger than 2 TB.

When the autocarve policy is **off**, all newly created units will consist of one single volume.

**Example:**

```
//localhost> /c0 show autocarve
/c0 Auto-Carving Policy = on
```

## /cx show carvesize

This feature only applies to 9000 series controllers.

This command shows the maximum size of the volumes that will be created if the autocarve policy is set to **on**. The carvesize can be set between 1024 GB and 2048 GB. Default carvesize is 2048 GB (2 TB). For more information see, “/cx show autocarve” above.

**Example:**

```
//localhost> /c0 show carvesize
/c0 Auto-Carving Size = 2000 GB
```

## /cx show memory

This command reports the size of the memory installed on the controller.



**Note:** The 9500S controllers ship with 128 MBytes of cache, yet only 112MB shows as memory installed. The other 16 MB is reserved for use by the controller.

**Example:**

```
//localhost> /c0 show memory
/c0 Memory Installed = 112MB
```

## /cx show autorebuild

This feature only applies to 9550SX, 9590SE, and 9650SE model controllers.

This command shows the Auto-Rebuild policy. If the policy is enabled, the firmware will select drives to use for rebuilding a degraded unit using the following priority order. For more information, see “/cx set autorebuild=on|off” on page 57.

1. Smallest usable spare.
2. Smallest usable unconfigured (available) drive.
3. Smallest usable failed drive.

If the policy is disabled, only spare drives will be used for an automatic rebuild operation.

### Example:

```
//localhost> /c0 show autorebuild
/c0 Auto-Rebuild Policy = on
```

## /cx show unitstatus

This command presents a list of units currently managed by the specified controller /cx, and shows their types, capacity, status, and unit policies.

Possible statuses include: OK, VERIFYING, VERIFY-PAUSED, INITIALIZING, INIT-PAUSED, REBUILDING, REBUILD-PAUSED, DEGRADED, MIGRATING, MIGRATE-PAUSED, RECOVERY, INOPERABLE, and UNKNOWN. (Definitions of the unit statuses are available in the *3ware Serial ATA RAID Controller User Guide*.)



**Note:** If an asterisk (\*) appears next to the status of a unit, there is an error on one of the drives in the unit. This feature provides a diagnostic capability for potential problem drives. The error may not be a repeated error, and may be caused by an ECC error, SMART failure, or a device error. Rescanning the controller will clear the drive error status if the condition no longer exists.

### Example:

```
//localhost> /c2 show unitstatus
```

Unit	UnitType	Status	%RCmpl	%V/I/M	Stripe	Size(GB)	Cache	AVrify
u0	RAID-5	OK	-	-	64K	596.004	ON	OFF
u1	RAID-0	OK	-	-	64K	298.002	ON	OFF
u2	SPARE	OK	-	-	-	149.042	-	OFF
u3	RAID-1	OK	-	-	-	149.001	ON	OFF

## /cx show allunitstatus

This command presents a count of total and Not Optimal units managed by the specified controller /cx. For more about the meaning of Not Optimal, see “Shell Object Commands” on page 23.

**Example:**

```
//localhost> /c0 show allunitstatus
/c0 Total Optimal Units = 2
/c0 Not Optimal Units = 0
```

## /cx show drivestatus

This command reports a list of drives and their port assignment, status, the unit with which they are associated, their size in gigabytes and blocks, and the serial number assigned by the drive manufacturer. (Definitions of the drive statuses are available in the *3ware Serial ATA RAID Controller User Guide*.)

**Example:**

```
//localhost> /c0 show drivestatus
```

Port	Status	Unit	Size	Blocks	Serial
p0	OK	u0	149.05 GB	312581808	3JS0TF14
p1	OK	u0	149.05 GB	312581808	3JS0TETZ
p2	OK	u1	149.05 GB	312581808	3JS0VG85
p3	OK	u1	149.05 GB	312581808	3JS0VGCY
p4	OK	u1	149.05 GB	312581808	3JS0VGGQ
p5	OK	u2	149.05 GB	312581808	3JS0VH1P
p6	OK	-	149.05 GB	312581808	3JS0TF0P
p7	OK	-	149.05 GB	312581808	3JS0VF43
p8	OK	-	149.05 GB	312581808	3JS0VG8D
p9	NOT-PRESENT	-	-	-	-
p10	NOT-PRESENT	-	-	-	-
p11	NOT-PRESENT	-	-	-	-

## /cx show all

This command shows the current setting of all of the following attributes on the specified controller: driver, model, memory, firmware, bios, monitor, serial, pcb, pchip, achip, numports, numunits, numdrives, unitstatus, drivestatus, allunitstatus, exportjbod, ondegrade, spinup, stagger and autocarve.

**Example:** (where *x* represents the actual version number)

```
//localhost> /c0 show all
/c0 Driver Version = 3.x
/c0 Model = 9550SX-12
/c0 Memory Installed = 112MB
/c0 Firmware Version = FE9X 3.x
/c0 Bios Version = BE9X 3.x
/c0 Monitor Version = BL9X 3.x
/c0 Serial Number = xxxxxx
/c0 PCB Version = Rev 0xx
/c0 PCHIP Version = 1.xx
/c0 ACHIP Version = 3.xx
/c0 Number of Ports = 12
/c0 Number of Units = 2
/c0 Number of Drives = 12
/c0 Total Optimal Units = 2
/c0 NotOptimalUnits = 0
/c0 Total Units = 2
/c0 JBOD Export Policy = off
/c0 Disk Spinup Policy = 7
/c0 Spinup Stagger Time Policy (sec) = 4
/c0 Cache on Degrade Policy = Follow Unit Policy
/c0 Auto-Carving Policy = off
/c0 Auto-Carving Size = 2047 GB
/c0 Auto-Rebuild Policy = enable
```

Unit	UnitType	Status	%RCmpl	%V/I/M	Stripe	Size(GB)	Cache	AVerify
u0	RAID-5	OK	-	-	256K	148.99	ON	ON
u1	RAID-5	OK	-	-	256K	595.961	ON	OFF

Port	Status	Unit	Size	Blocks	Serial
p0	OK	u0	74.53 GB	156301488	3JV3MV1C
p1	OK	u0	74.53 GB	156301488	3JV3MK6B
p2	OK	u0	74.53 GB	156301488	3JV3LW52
p3	OK	u1	74.53 GB	156301488	3JV49S77
p4	OK	u1	74.53 GB	156301488	3JV3MVTA
p5	OK	u1	74.53 GB	156301488	5JV980Z0
p6	OK	u1	74.53 GB	156301488	5JV9820G
p7	OK	u1	111.79 GB	234441648	WD-WMAEL10275
p8	OK	u1	111.79 GB	234441648	WD-WMAEL10274
p9	OK	u1	111.79 GB	234441648	WD-WMAEL10281
p10	OK	u1	111.79 GB	234441648	WD-WMAEL10273
p11	OK	u1	111.79 GB	234441648	WD-WMAEL10274

Name	OnlineState	BBUReady	Status	Volt	Temp	Hours	LastCapTest
bbu	On	Yes	OK	OK	OK	165	06-Nov-2004

```

/cx add type=<RaidType> disk=<p:-p>
[stripe=Stripe] [noscan] [group=<3/4/5/6/7/8>]
[nocache] [autoverify] [noqpolicy][ignoreECC]
[name=string]
[storsave=<protect|balance|perform>]

```

This command allows you to create a new unit on the specified controller. You specify *type*, *disks*, and optional *stripe* size. By default the host operating system will be informed of the new block device, write cache will be enabled, and a storsave policy of protect will be set. In case of RAID 50, you can also specify the layout of the unit by specifying the number of disks per disk group with the *group* attribute.

*/cx* is the controller name, for example */c0*, */c1*, and so forth.

**type=RaidType** specifies the type of RAID unit to be created. Possible unit types include raid0, raid1, raid5, raid6 (9650SE only), raid10, raid50, single, spare, and JBOD.

**Example:** `type=raid5`

When a new unit is created, it is automatically assigned a unique serial number. In addition, users can assign the unit a name.



**Note:** The unit's serial number cannot be changed.

The following table shows supported types and controller models.

**Table 6: Supported RAID Types**

Model	R0	R1	R5	R6	R10	R50	Single	JBOD	Spare
7K/8K	Yes	Yes	Yes	No	Yes	No	No	Yes	Yes
9000 <sup>a</sup>	Yes	Yes	Yes	No	Yes	Yes	Yes	Yes	Yes
9650SE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes

a. Models 9500S, 9550SX, and 9590SE

**disk=p:-p** consists of a list of ports (disks) to be used in the construction of the specified unit type. One or more ports can be specified. Multiple ports can be specified using a colon (:) or a dash (-) as port index separators. A dash indicates a range and can be mixed with colons. For example `disk=0:1:2-5:9:12` indicates port 0, 1, 2 through 5 (inclusive), 9 and 12.

**stripe=Stripe** consists of the stripe size to be used. The following table illustrates the supported and applicable stripes on unit types and controller models. Stripe size units are in K (kilobytes). If no stripe size is specified, 64K is used by default, if applicable. If you need to change the stripe size after the unit is created, you can do so by migrating the unit.

**Table 7: Supported Stripe Sizes (KB)**

Model	R0	R1	R5	R6	R10	JBOD	Spare	R50	Single
7K/8K	64	N/A	64	N/S	64	N/A	N/A	N/S	N/S
	128				128				
	256				256				
	512				512				
	1024				1024				
9000 <sup>a</sup>	16	N/A	16	N/S	16	N/A	N/A	16	N/A
	64		64		64			64	
	256		256		256			256	
9650SE	16	N/A	16		16	N/A	N/A	16	N/A
	64		64	64	64			64	
	256		256		256			256	

a. Models 9500S, 9550SX, and 9590SE

**group=3/4/5/6/7/8** indicates the number of disks per group for a RAID 50 type. (This attribute can only be used when type=raid50.) Recall that a RAID 50 is a multi-tier array. At the bottom-most layer, N number of disks per group are used to form the RAID 5 layer. These RAID 5 arrays are then integrated into a RAID 0. This attribute allows you to specify the number of disks in the RAID 5 level. Valid values are 3, 4, 5, 6, 7, and 8.

Note that a sufficient number of disks are required for a given pattern or disk group. For example, given 6 disks, specifying 3 will create two RAID 5 arrays. With 12 disks, specifying 3 will create four RAID 5 arrays under the RAID 0 level. With only 6 disks a grouping of 6 is not allowed, as you would basically be creating a RAID 5.

The default RAID 50 grouping varies, based on number of disks. For 6 and 9 disks, default grouping is 3. For 8 disks, the default grouping is 4. For 10 disks, the default grouping is 5, and for 12 disks, the disks can be grouped into groups of 3, 4, or 6 drives (the group of 4 drives is set by default as it provides the best of net capacity and performance). For 15 disks, the disks can be

grouped into groups of 3 or 5 drives. For 16 disks, the disks can be grouped into groups of 4 or 8 drives.

**noscan** attribute instructs CLI not to notify the operating system of the creation of the new unit. By default CLI will inform the operating system. One application of this feature is to prevent the operating system from creating block special devices such as /dev/sdb and /dev/sdc as some implementations might create naming fragmentation and a moving target.

**nocache** attribute instructs CLI to disable the write cache on the newly created unit. Enabling write cache increases write performance at the cost of potential data loss in case of sudden power loss (unless a BBU or UPS is installed). By default the cache is enabled. To avoid the possibility of data loss in the event of a sudden power loss, it is recommended not to set nocache unless there is a BBU (battery backup unit) or UPS (uninterruptible power supply) installed.

**autoverify** attribute enables the autoverify attribute on the unit that is to be created. For more details on this feature, see “/cx/ux set autoverify=on|off” on page 68. This feature is not supported on model 7000/8000. On model 9000, the JBOD autoverify attribute is not persistent (does not survive reboots).

**noqpolicy** attribute instructs CLI to disable the qpolicy (drive queuing) on the newly created unit. The default is for the qpolicy to be on (in other words, noqpolicy is not specified). For a spare unit, specifying noqpolicy has no effect and the default remains. If the spare unit becomes a true unit, it would adopt the qpolicy of the “new” unit. For JBOD, the qpolicy cannot be set during unit creation, and specifying noqpolicy returns an error. For more about drive queuing, see “/cx/ux show qpolicy” on page 62 and “/cx/ux set qpolicy=on|off” on page 70.

**ignoreECC** attribute enables the ignoreECC/OverwriteECC attribute on the unit that is to be created. For more details on this feature, see “/cx/ux set ignoreECC=on|off” on page 69. The following table illustrates the supported Model-Unit Types. This table only applies to setting this feature at unit creation time. IgnoreECC only applies to redundant units. For the 7/8000 series, this setting is only applicable during rebuild; it is not applicable during creation.

**Table 8: Supported Model-Unit Types for ignoreECC**

Model	R-0	R-1	R-5	R-6	R-10	R-50	Single	JBOD	Spare
7K/8K	No	No	No	N/A	No	No	No	No	No
9000 <sup>a</sup>	No	Yes	Yes	N/A	Yes	Yes	No	No	No
9650SE	No	Yes	Yes	Yes	Yes	Yes	No	No	No

a. Models 9500S, 9550SX, and 9590SE



**name=string** attribute allows you to name the new unit. (This feature is for 9000 series and above controllers.) The string can be up to 21 characters and cannot contain spaces. In order to use reserved characters (<, >, !, &, etc.) put double quotes (" ") around the name string. The name can be changed after the unit has been created. For more information, see “/cx/ux set name=string” on page 70 and “/cx/ux show name” on page 62.

**storsave=protect|balance|perform** attribute allows user to set the storsave policy of the new unit. This feature is only for 9550SX, 9590SE, and 9650SE controllers. For more information, see “/cx/ux set storsave=protect|balance|perform [quiet]” on page 70.

## /cx rescan [noscan]

This command instructs the controller to rescan all ports and reconstitute all units. The controller will update its list of ports (attached disks), and attempts to read every DCB (Disk Configuration Block) in order to re-assemble its view and awareness of logical units. Any newly found unit(s) or drive(s) will be listed.

**noscan** is used to not inform the operating system of the unit discovery. The default is to inform the operating system.



**Note:** If you are adding new drives, add them physically before issuing the rescan commands. Hot swap carriers are required unless you first power-down the system to prevent system hangs and electrical damage.

### Example:

```
//localhost> /c1 rescan
Rescanning controller /c1 for units and drives ...Done
Found following unit(s): [/c1/u3]
Found following drive(s): [/c1/p7, /c1/p8]
```



**Note:** Rescanning does not import non-JBOD on 7000/8000 models.

## /cx commit

This command only applies to the Windows operating system. It commits all changes if a faster shutdown method is needed when running certain database applications. Linux and FreeBSD file systems do not require this command since they have their own ways of notifying the controller to do clean up for shut down.

## /cx flush

This command forces the controller to write all cached data to disk for the specified controller.

## /cx update fw=*filename\_with\_path* [force]

This command is only for 9000 series controllers.

This command allows the downloading of the specified firmware image to the corresponding controller.

**Note:** Before issuing this command, you must have already obtained the firmware image and placed it on your system. You can obtain the firmware image from the 3ware website: <http://www.3ware.com/downloads>.

**fw=*filename\_with\_path*** attribute allows you to specify the firmware image file name along with its absolute path. The new image specified by this *filename\_with\_path* is checked for compatibility with the current controller, current driver, and current application versions. A recommendation is then made as to whether an update is needed, and you are asked to confirm whether you want to continue. If you confirm that you want to continue, the new firmware image is downloaded to the specified controller.

A reboot is required for the new firmware image to take effect.

### Example:

```
//localhost> /c0 update fw=/tmp/prom0006.img
Warning: We strongly recommend backing up your data before
updating the firmware. Updating the firmware can render the
device driver and/or management tools incompatible. It is
recommended to have a copy of current firmware image for
rollbacks.
```

```
Examining compatibility data from firmware image and /c0 ...
```

```
Done.
```

New-Firmware	Current-Firmware	Current-Driver	Current-API
FE9X 3.05.00.005	FE9X 3.05.00.005	2.26.04.007	2.01.00.008

```
Current firmware version is the same as the new firmware.
```

```
Recommendation: No need to update.
```

```

Given the above recommendation...
Do you want to continue ? Y|N [N]: y
Downloading the firmware from file /tmp/prom0006.img ... Done.
The new image will take effect after reboot.

```

**force** attribute is optional. If you include it, the compatibility checks are bypassed.

## /cx show alarms [reverse]

Asynchronous events (also referred to as AENs or alarms) are originated by firmware and captured by their respective device drivers. These events reflect warning, debugging, and/or informative messages for the end user. These events are kept in a finite queue inside the kernel, awaiting extraction by user space programs such as CLI and/or 3DM.

The /cx show alarms command displays all available alarms on a given controller. The default is to display the most recent alarm or AEN message first. The user can also use the **[reverse]** attribute to display the most recent alarm or AEN message last.

Alarms generated on 7000/8000 controllers do not have dates, so you will see a '-' in the Date column. This means that it is not applicable. In addition, alarm messages on 7000/8000 controllers contain the severity in the message text, so the Severity column also shows a '-'.

Typical output looks like:

```

tw_cli> /cl show alarms reverse
Ctl Date                               Severity Message
-----
c1 [Fri Nov 28 04:26:31 2003] ERROR (0x04:0x0002): Degraded unit detected:unit=0, port=2
c1 [Fri Nov 28 06:13:54 2003] INFO (0x04:0x000B): Rebuild started: unit=0
c1 [Fri Nov 28 06:30:35 2003] INFO (0x04:0x003B): Background rebuild paused:unit=0
c1 [Fri Nov 28 06:33:00 2003] ERROR (0x04:0x0002): Degraded unit detected:unit=0, port=0
c1 [Fri Nov 28 06:33:04 2003] ERROR (0x04:0x0002): Degraded unit detected:unit=0, port=4
c1 [Fri Nov 28 06:33:46 2003] INFO (0x04:0x000B): Rebuild started: unit=0
c1 [Fri Nov 28 06:37:58 2003] INFO (0x04:0x000B): Rebuild started: unit=0
c1 [Fri Nov 28 07:51:34 2003] INFO (0x04:0x0005): Background rebuild done:unit=0
c1 [Fri Nov 28 07:59:43 2003] INFO (0x04:0x0005): Background rebuild done:unit=0
c1 [Mon Dec 1 02:26:12 2003] ERROR (0x04:0x0002): Degraded unit detected:unit=0, port=3

```

## /cx show diag

This command extracts controller diagnostics suitable for technical support usage. Note that some characters might not be printable or rendered correctly (human readable). It is recommended to save the output from this command to a file, where it can be communicated to technical support or further studied with Linux utilities such as `od(1)`.

In order to redirect the output you must run the following command from a command line, not from within the `tw_cli` shell.

```
tw_cli /c0 show diag > diag.txt
```

## /cx show rebuild

9000 series controllers support background tasks and allow you to schedule a regular time when they occur.

Rebuild is one of the supported background tasks. Migrate and initialize are other background tasks that follow the same schedule as rebuild. Other background tasks for which there are separate schedules are verify and selftest. For each background task, up to 7 time periods can be registered, known as slots 1 through 7. Each task schedule can be managed by a set of commands including **add**, **del**, **show** and **set** a task. Background task schedules have a slot id, start-day-time, duration, and status attributes.

For details about setting up a schedule for background rebuild tasks, see “Setting Up a Rebuild Schedule” on page 50.

Rebuild activity attempts to (re)synchronize all members of redundant units such as RAID-1, RAID-10, RAID-5 and RAID-50. Rebuild can be started manually or automatically if a spare has been defined. Scheduled rebuilds will take place during the scheduled time slot, if enabled the schedules are enabled. For in depth information about rebuild and other background tasks, see “About Background Tasks” in the *3ware Serial ATA RAID Controller User Guide*.

The **show rebuild** command displays the current rebuild background task schedule as illustrated below.

```
//localhost> /c1 show rebuild
Rebuild Schedule for Controller /c1
=====
Slot    Day    Hour          Duration      Status
-----
1       Mon    2:00pm        10 hr(s)     disabled
2       Thu    7:00pm        18 hr(s)     disabled
3       -      -             -            disabled
4       -      -             -            disabled
5       -      -             -            disabled
6       Mon    1:00am        4 hr(s)      disabled
7       Sun    12:00am       1 hr(s)      disabled
```

A status of “disabled” indicates that the task schedule is disabled. In this case, the controller will not use the defined schedule timeslots. If the rebuild command is entered manually, rebuilding will start within 10 to 15 minutes. It will begin automatically if a rebuild is needed and a proper spare drive is set up.

If the rebuild schedule is enabled while a rebuild process is underway, the rebuild will pause until a scheduled time slot.

#### Example:

If a unit is in the initialization state at noon on Wednesday and the rebuild schedule shown above is in use (with schedules disabled), you would see the following status using the show command:

```
$ tw_cli /cl show
```

Unit	UnitType	Status	%RCmpl	%V/I/M	Stripe	Size(GB)	Cache	AVrfy
u0	RAID-5	INITIALIZING	0	-	64K	521.466	ON	OFF

Port	Status	Unit	Size	Blocks	Serial
p0	NOT-PRESENT	-	-	-	-
p1	OK	u0	76.33 GB	160086528	Y2NXL7FE
p2	NOT-PRESENT	-	-	-	-
p3	OK	u0	76.33 GB	160086528	Y2NXLB9E
p4	NOT-PRESENT	-	-	-	-
p5	OK	u0	76.33 GB	160086528	Y2NXQPZE
p6	NOT-PRESENT	-	-	-	-
p7	OK	u0	76.33 GB	160086528	Y2NXM4VE
p8	OK	u0	74.53 GB	156301488	3JV3WTSE
p9	OK	u0	74.53 GB	156301488	3JV3WRHC
p10	OK	u0	74.53 GB	156301488	3JV3WQLQ
p11	OK	u0	74.53 GB	156301488	3JV3WQLZ

Name	OnlineState	BBUReady	Status	Volt	Temp	Hours	LastCapTest
bbu	On	Yes	OK	OK	OK	0	xx-xxx-xxxx

If you then enable the rebuild schedules, the unit initialization will be paused until the next scheduled time slot, as reflected in the examples below:

```
//localhost> /cl set rebuild=enable
Enabling scheduled rebuilds on controller /cl ...Done.
```

```
//localhost> /cl show rebuild
Rebuild Schedule for Controller /cl
```

Slot	Day	Hour	Duration	Status
1	Mon	2:00pm	10 hr(s)	enabled
2	Thu	7:00pm	18 hr(s)	enabled
3	-	-	-	-
4	-	-	-	-
5	-	-	-	-
6	Mon	1:00am	4 hr(s)	enabled
7	Sun	12:00am	1 hr(s)	enabled

```
$ tw_cli /cl show
```

Unit	UnitType	Status	%RCmpl	%V/I/M	Stripe	Size(GB)	Cache	AVrfy
------	----------	--------	--------	--------	--------	----------	-------	-------

```

-----
u0    RAID-5    INITIALIZING  0    -    64K    521.466    ON    OFF

Port  Status          Unit  Size          Blocks        Serial
-----
p0    NOT-PRESENT    -    -            -            -
p1    OK              u0    76.33 GB     160086528    Y2NXL7FE
p2    NOT-PRESENT    -    -            -            -
p3    OK              u0    76.33 GB     160086528    Y2NXLB9E
p4    NOT-PRESENT    -    -            -            -
p5    OK              u0    76.33 GB     160086528    Y2NXQPZE
p6    NOT-PRESENT    -    -            -            -
p7    OK              u0    76.33 GB     160086528    Y2NXM4VE
p8    OK              u0    74.53 GB     156301488    3JV3WTSE
p9    OK              u0    74.53 GB     156301488    3JV3WRHC
p10   OK              u0    74.53 GB     156301488    3JV3WQLQ
p11   OK              u0    74.53 GB     156301488    3JV3WQLZ

Name  OnlineState  BBUReady  Status  Volt  Temp  Hours  LastCapTest
-----
bbu   On           Yes       OK      OK    OK    0      xx-xxx-xxxx

```

## /cx show verify

9000 series controllers support background tasks and allow you to schedule a regular time when they occur.

Verify is one of the supported background tasks. Rebuild and selftest are other background tasks for which there are separate schedules. Migrate and initialize are additional background tasks that follow the same schedule as rebuild. For each background task, up to 7 time periods can be registered, known as slots 1 through 7. Each task schedule can be managed by a set of commands including **add**, **del**, **show** and **set** a task. Background task schedules have a slot id, start-day-time, duration, and status attributes.

For details about setting up a schedule for background verify tasks, see “Setting Up a Verify Schedule” on page 51.

**Verify** activity verifies all units based on their unit type. Verifying RAID 1 involves checking that both drives contain the exact data. On RAID 5 and RAID 6, the parity information is used to verify data integrity. RAID 10 and 50 are composite types and follow their respective array types. On 9000 series, non-redundant units such as RAID 0, JBOD, single, and spare, are also verified (by reading and reporting un-readable sectors). If any parity mismatches are found, the array will be automatically background initialized. (For information about the initialization process, see the user guide that came with your 3ware RAID controller.)

The **show verify** command displays the current verify background task schedule as illustrated below.

```
//localhost> /c1 show verify
Verify Schedule for Controller /c1
=====
Slot      Day      Hour      Duration      Status
-----
1         Mon      2:00am    4 hr(s)       disabled
2         -        -         -             disabled
3         Tue      12:00am   24 hr(s)      disabled
4         Wed      12:00am   24 hr(s)      disabled
5         Thu      12:00am   24 hr(s)      disabled
6         Fri      12:00am   24 hr(s)      disabled
7         Sat      12:00am   24 hr(s)      disabled
```

A status of “disabled” indicates that the controller will not use the defined schedule timeslots and will start verifying immediately (within 10 to 15 minutes), if the verify command is entered manually, or it will begin automatically if the autoverify option is set. Rebuilds, migrations, and initializations will take priority over verifies.

## /cx show selftest

9000 series controllers support background tasks and allow you to schedule a regular time when they occur.

Selftest is one of the supported background tasks. Rebuild and verify are other background tasks for which there are separate schedules. Migrate and initialize are additional background tasks that follow the same schedule as rebuild. For each background task, up to 7 time periods can be registered, known as slots 1 through 7. Each task schedule can be managed by a set of commands including **add**, **del**, show and **set** a task. Background task schedules have a slot id, start-day-time, duration, and status attributes.

For details about setting up a schedule for background selftest tasks, see “Setting Up a Selftest Schedule” on page 52.

**Selftest** activity provides two types of selftests; UDMA (Ultra Direct Memory Access) and SMART (Self Monitoring Analysis and Reporting). Both self tests are checked once each day by default.

UDMA self test entails checking the current ATA bus speed (between controller and attached disk), which could have been throttled down during previous operations and increase the speed for best performance (usually one level higher). Possible speeds include 33, 66, 100 and 133 Mhz (at this writing). Note that UDMA selftest is not applicable (or required) with SATA drives, but is left enabled by default.

SMART activity instructs the controller to check certain SMART supported thresholds by the disk vendor. An AEN is logged to the alarms page if a drive reports a SMART failure.

The **show selftest** command displays the current selftest background task schedule as illustrated below. Selftests do not have a time duration since they are completed momentarily.

```
//localhost> /c1 show selftest
```

```
Selftest Schedule for Controller /c1
=====
Slot      Day      Hour      UDMA      SMART
-----
1         Sun      12:00am   enabled   enabled
2         Mon      12:00am   enabled   enabled
3         Tue      12:00am   enabled   enabled
4         Wed      12:00am   enabled   enabled
5         Thu      12:00am   enabled   enabled
6         Fri      12:00am   enabled   enabled
7         Sat      12:00am   enabled   enabled
```

## */cx add rebuild=ddd:hh:duration*

This command adds a new background rebuild task to be executed on the day *ddd* (where *ddd* is Sun, Mon, Tue, Wed, Thu, Fri, and Sat), at the hour *hh* (range 0 .. 23), for a duration of *duration* (range 1 .. 24) hours. A maximum of seven rebuild tasks can be scheduled. This command will fail if no (empty) task slot is available.

### Example:

```
//localhost> /c1 add rebuild=Sun:16:3
```

adds a rebuild background task schedule to be executed on Sundays at 16 hours (4:00 PM) for a duration of 3 hours.

## Setting Up a Rebuild Schedule

Setting up a rebuild schedule requires several steps, and several different CLI commands in addition to **/cx add rebuild**.

### To set up the rebuild schedule you want to use, follow this process:

- 1 Use the **/cx show rebuild** command to display the current schedule for rebuild tasks. (For details, see page 46.)
- 2 If any of the scheduled tasks do not match your desired schedule, use the **/cx del rebuild** command to remove them. (For details, see page 53.)



- 3 Use the **/cx add rebuild** command to create the rebuild schedule slots you want (described above.)
- 4 Use the **/cx set rebuild=enable** command to enable the schedule (this enables all rebuild schedule slots). (For details, see page 53.)



**Warning:** If all time slots are removed, be sure to also disable the schedule. Otherwise the applicable background task will never occur.

## */cx add verify=ddd:hh:duration*

This command adds a new background verify task to be executed on the day *ddd* (where *ddd* is Sun, Mon, Tue, Wed, Thu, Fri, and Sat), at hour *hh* (range 0 .. 23), for a duration of *duration* (range 1 .. 24) hours. A maximum of seven verify tasks can be scheduled. This command will fail if no (empty) task slot is available.

### **Example:**

```
//localhost> /cl add verify=Sun:16:3
```

adds a verify background task schedule to be executed on Sundays at 16 hours (4:00 PM) for a duration of 3 hours.

## **Setting Up a Verify Schedule**

Setting up a verify schedule requires several steps, and several different CLI commands in addition to **/cx add verify**.

### **To set up the verify schedule you want to use, follow this process:**

- 1 Use the **/cx show verify** command to display the current schedule for verify tasks. (For details, see page 48.)
- 2 If any of the scheduled tasks do not match your desired schedule, use the **/cx del verify** command to remove them. (For details, see page 53.)
- 3 Use the **/cx add verify** command to create the verify schedule slots you want (described above.)
- 4 Use the **/cx set verify=enable** command to enable the schedule (this enables all rebuild schedule slots). (For details, see page 54.)
- 5 Use the **/cx/ux set autoverify=on** command to turn on autoverify for each unit you want to follow the schedule. (For details, see page 68.)



**Note:** If you do not enable autoverify for units or start a verification manually, your verify schedule will not run, even if it is enabled with the `/cx set verify=enable` command.



**Warning:** If all time slots are removed, be sure to also disable the schedule. Otherwise the applicable background task will never occur

## `/cx add selftest=ddd:hh`

This command adds a new background selftest task to be executed on the day *ddd* (where *ddd* is Sun, Mon, Tue, Wed, Thu, Fri, and Sat), at hour *hh* (range 0 .. 23). Notice that selftest runs to completion and as such no duration is provided. A maximum of seven selftest tasks can be scheduled. This command will fail if no (empty) task slot is available.

### Example:

```
//localhost> /c1 add selftest=Sun:16
```

adds a selftest background task schedule to be executed on Sundays at 16 hours (4:00 PM).

## Setting Up a Selftest Schedule

Setting up a selftest schedule requires several steps, and several different CLI commands in addition to `/cx add selftest`.

### To set up the selftest schedule you want to use, follow this process:

- 1 Use the `/cx show selftest` command to display the current schedule for selftest tasks. (For details, see page 49.)
- 2 If any of the scheduled tasks do not match your desired schedule, use the `/cx del selftest` command to remove them. (For details, see page 53.)
- 3 Use the `/cx add selftest` command to create the selftest schedule slots you want (described above.)
- 4 Use the `/cx set selftest=enable` command to enable the schedule (this enables all selftest schedule slots). (For details, see page 54.)

## `/cx del rebuild=slot_id`

This command removes the rebuild background task in slot *slot\_id*.

**Example:**

```
//localhost> /c1 del rebuild=2
```

removes the rebuild background task in slot 2.



**Warning:** If all time slots are removed, be sure to also disable the schedule. Otherwise the applicable background task will never occur

## `/cx del verify=slot_id`

This command removes the verify background task in slot *slot\_id*.

**Example:**

```
//localhost> /c1 del verify=3
```

removes verify background task in slot 3.



**Warning:** If all time slots are removed, be sure to also disable the schedule. Otherwise the applicable background task will never occur

## `/cx del selftest=slot_id`

This command removes (or unregisters) the selftest background task in slot *slot\_id*.

**Example:**

```
//localhost> /c1 del selftest=3
```

Will remove selftest background task in slot 3.



**Warning:** If all time slots are removed, be sure to also disable the schedule. Otherwise the selftest background task will never occur.

## `/cx set rebuild=enable|disable|1..5`

This command enables or disables all rebuild background task slots on controller `/cx` and sets the priority of rebuild versus I/O operations. When enabled, rebuild tasks will only be run during the time slots scheduled for rebuilds. If a rebuild is taking place when the schedule is enabled, it will be paused until the next scheduled time.

The priority of rebuild versus I/O operations is specified with *1..5*, where 1 is more resources and 5 the least. Setting the value to 1 gives maximum processing time to rebuilds rather than I/O. Setting the value to 5 gives maximum processing time to I/O rather than rebuilds.

Enabling and disabling rebuild schedules is only for 9000 models, however the rebuild rate (**1..5**) applies to all controllers.

7000- and 8000-series controllers have only one setting for Task Rate; it applies to both rebuild and verify rates. This rate is not persistent following a reboot for 7000- and 8000-series controllers.

## `/cx set verify=enable|disable|1..5`

This command enables or disables all verify background task slots on controller `/cx` and (when enabled) sets the priority of verification versus I/O operations. When enabled, verify tasks will only be run during the time slots scheduled for verifies. If a verify is taking place when the schedule is enabled, it will be paused until the next scheduled time.

The priority of verify versus I/O operations is specified with *1..5*, where 1 is more resources and 5 the least. Setting this value to 1 implies fastest verify, and 5 implies fastest I/O.

Enabling and disabling verify schedules is only for 9000 models, however the verify rate (**1..5**) applies to all controllers.



**Note:** When enabling the verify schedule you must also remember to enable the `autoverify` setting for the units to be verified. For more information see `/cx/ux set autoverify=on|off` on page 68.

## `/cx set selftest=enable|disable [task=UDMA|SMART]`

This command enables or disables all selftest tasks or a particular `selftest_task` (UDMA or SMART).

Enabling and disabling selftest is only for 9000 models. 7/8000 models have the same internal schedule, but it is not viewable or changeable.

### **Example:**

```
//localhost> /c0 selftest=enable task=UDMA
```

enables UDMA selftest on controller c0.

## `/cx set exportjbod=on|off`

This command allows you to set the JBOD Export Policy to **on** or **off**. By default, `exportjbod` is **off**.

If the JBOD export policy is **off**, CLI will not be able to create JBODs. During reboot, firmware will not export JBOD units to the operating system.

The JBOD Export Policy is only supported on 9000-series controllers. Previous models did not have such a policy enforcement feature.

A JBOD is an unconfigured disk attached to your 3ware RAID controller. AMCC recommends that you use Single Disk as a replacement for JBOD, to take advantage of features such as RAID level migration.

## `/cx set ondegrade=cacheoff|follow`

This command is only for 9500S controllers.

This command allows you to set a controller-based write cache policy. If the policy is set to **cacheoff** and a unit degrades, the firmware will disable the write-cache on the degraded unit, regardless of what the unit-based write cache policy is. If the policy is set to **follow** and a unit degrades, firmware will follow whatever cache policy has been set for that unit. (For details about the unit-based policy, see “`/cx/ux set cache=on|off [quiet]`” on page 68.)

## `/cx set spinup=nn`

This command is only for 9000 series controllers.

This command allows you to set a controller-based Disk Spinup Policy that specifies how many drives can spin up at one time. The value must be a positive integer between 1 and the number of disks/ports supported on the controller (4, 8, or 12). The default is 1.

This policy is used to stagger spinups of disks at boot time in order to spread the power consumption on the power supply. For example, given a spinup policy of 2, the controller will spin up two disks at a time, pause, and then spin up another 2 disks. The amount of time to pause can be specified with the Spinup Stagger Time Policy (`/cx set stagger`).

Not all drives support staggered spinup. If you enable staggered spinup and have drives that do not support it, the setting will be ignored.

## /cx set stagger=*nn*

This command is only for 9000 series controllers.

This command allows you to set a controller-based Disk Spinup Stagger Time Policy that specifies the delay between spin-ups. The value must be a positive integer between 0 to 60 seconds. This policy, in conjunction with Disk Spinup Policy, specifies how the controller should spin up disks at boot time. The default is 6 seconds.

## /cx set autocarve=*on|off*

This command is only for 9000 series controllers.

This command allows you to set the auto-carve policy to **on** or **off**. By default, autocarve is **off**.

When the auto-carve policy is set to **on**, any unit larger than the carvesize is created or migrated into one or more carvesize volumes and a remaining volume. Each volume can then be treated as an individual disk with its own file system. The default carvesize is 2 TB.

This feature is useful for operating systems limited to 2TB file systems.

For example, using the 2 TB default carvesize, a 3 TB unit will be configured into one 2 TB volume and one 1 TB volume. A 5 TB unit will be configured into two 2 TB volumes and one 1 TB volume.

When auto-carve policy is set to **off**, all new units are created as a single large volume. If the operating system can only recognize up to 2 TBs, space over 2 TB will not be available.

**Example:**

```
//localhost> /c0 set autocarve=on
Setting Auto-Carving Policy on /c0 to on ... Done.
```

## /cx set carvesize=*[1024..2048]*

This command is only for 9000 series controllers.

This command allows you to set the carve size in GB. This feature works together with autocarve. See “/cx set autocarve=*on|off*” above for details.

**Example:**

```
//localhost> /c0 set carvesize=2000
Setting Auto-Carving Size on /c0 to 2000 GB ... Done.
```

## /cx set autorebuild=on|off

This command is only for 9550SX , 9590SE, and 9650SE controllers.

This command turns the Auto-Rebuild policy on or off. By default, autorebuild is on.

If the policy is on the firmware will select drives to use for rebuilding a degraded unit using the following priority order.

1. Smallest usable spare.
2. Smallest usable unconfigured (available) drive.
3. Smallest usable failed drive.



**Note:** Failed drives can be drives that have mechanically failed, or they can be drives that have been disconnected from the controller long enough for the controller to classify them as failed.

Enabling Auto-Rebuild allows you to add a drive to the controller and have it be available for a rebuild as soon as you tell the controller to rescan, without having to specify it as a spare. It also means that if you accidentally disconnect a drive (causing the controller to see it as a failed drive) and then reconnect it, the controller will automatically try to use it again.

If the policy is off, spares are the only candidates for rebuild operations.

### Example:

```
//localhost> /c0 set autorebuild=enable
Setting Auto-Rebuild Policy on /c0 to enable ... Done.
```

## /cx set autodetect=on|off disk=<p:-p>|all

This command is only for 9000 series controllers.

This command is associated with the staggered spin-up feature when hot-swapping drives. When staggered spin-up is enabled (see command /cx set spinup and /cx set stagger), during a reset or power on, the controller will spin up all detected drives with a delay between each spinup, allowing the spread of power consumption on the power supply. When a drive is hot-swapped, (as opposed to when it has just been powered on or reset), the default behavior of the system is immediate spin-up. This command can change the default behavior and set the controller to do a staggered spinup for hot-swapped drives.



**Note:** The autodetect setting cannot be shown in CLI or displayed in 3DM or 3BM. This feature may be added in a future release.

**autodetect=on|off** enables or disables automatic detection of drives on the controller's ports for staggered spin-up.

**disk=<p:-p>|all** specifies one or many disks (that is, drives or ports). If a port is empty (no drive is inserted), this feature is disabled for that port and its port number is shown. The example below shows that autodetect has been set to **off** to initiate staggered spin-up during hot-swapping, where port 3 was empty and ports 5 and 6 had drives inserted.

**Example:**

```
//localhost>> /c0 set autodetect=off disk=3:5-6
Setting Auto-Detect on /c0 to [off] for port [3] and for disk
[5,6]... Done
```

If “disk=all,” then all of the drives or ports for that controller are specified. For example:

```
//localhost>> /c0 set autodetect=off disk=all
Setting Auto-Detect on /c2 to [off] for all disks/ports... Done.
```

**Usage Scenario:**

If you are hot-plugging a large number of drives at the same time and are concerned that you might overload the power supply, you might use this command as follows:

- 1 Issue the command (set autodetect=off) to disable automatic detection of the ports for staggered spin-up.
- 2 If the ports are not empty, pull the drives out of the specified ports.
- 3 Insert (or replace) the drives at the ports specified.
- 4 Issue the command (set autodetect=on) to enable auto detect of the ports with the newly inserted drives.

The preceding steps would spin up the newly inserted drives in a staggered manner. Please note that the command takes longer for ports that do not have drives inserted, since the controller allows time for the empty ports to respond.

## /cx start mediascan

This command applies only to 7000/8000 controllers. For 9000 series controllers, use the verify command.

This command provides media scrubbing for validating the functionality of a disk, including bad block detection, remapping, and so forth. The command starts a media scan operation on the specified controller /cx.



## /cx stop mediascan

This command applies only to 7000/8000 controllers.

This command stops a media scan operation on the specified controller /cx. (Media scans are started using **/cx start mediascan**.)

## Unit Object Commands

Unit Object commands provide information and perform actions related to a specific unit, such as /c0/u1 (unit 1 on controller 0). For example, you use logical disk object commands for such tasks as seeing the rebuild, verify, or initialize status of a unit, starting, stopping, and resuming rebuilds and verifies, and setting policies for the unit.

### Syntax

```

/cx/ux show
/cx/ux show attribute [attribute ...] where attributes are:
    initializestatus|cache|name(9000 series)|
    qpolicy(9550SX, 9590SE, 9650SE)|rebuildstatus|
    serial(9000 series)|status|verifystatus|
    storsave(9550SX, 9590SE, 9650SE)|volumes(9000 series)|
    ignoreECC (9000 series)|identify (9550SX, 9590SE,
    9650SE)
/cx/ux show all

/cx/ux start rebuild disk=<p:-p...> [ignoreECC]
/cx/ux start verify
/cx/ux pause rebuild (7000/8000 only)
/cx/ux resume rebuild (7000/8000 only)
/cx/ux stop verify
/cx/ux flush
/cx/ux del [noscan] [quiet]
/cx/ux set autoverify=on|off
/cx/ux set cache=on|off [quiet]
/cx/ux set identify=on|off (9550SX, 9590SE, 9650SE only)
/cx/ux set ignoreECC=on|off
/cx/ux set qpolicy=on|off (9550SX, 9590SE, 9650SE only)
/cx/ux set name=string (9000 series)
/cx/ux set storsave=protect|balance|perform [quiet](9550SX,
    9590SE, 9650SE)
/cx/ux migrate type=RaidType [disk=p:-p] [group=3|4|5|6|7|8]
    [stripe=Stripe] [noscan] [nocache] [autoverify]
    (9000 series) RaidType = {raid0, raid1, raid5,
    raid6(9650SE only), raid10, raid50, single}
/cx/ux remove [noscan] [quiet]

```

## /cx/ux show

This command shows summary information about the specified unit **/cx/ux**. If the unit consists of sub-units as with the case of RAID-1, RAID-5, RAID-10, RAID-50, then each sub-unit is further presented. If the Auto-Carving policy was on at the time the unit was created and the unit is over the carve size, multiple volumes were created and are displayed at the end of the summary information. Similarly, if the unit was created using the 3ware BIOS utility 3BM and a size was entered in the Boot Volume Size field, multiple volumes were created and will be displayed. (Note that a volume created using the Boot Volume Size feature does not have to be used as a boot volume.)

One application of the **/cx/ux show** command is to see which sub-unit of a degraded unit has caused the unit to degrade and which disk within that sub-unit is the source of degradation. Another application is to see the source and destination units during a migration.

**Example:**

```
//localhost> /c0/u0 show
```

Unit	UnitType	Status	%RCmpl	%V/I/M	Port	Stripe	Size(GB)
u0	RAID-50	OK	-	-	-	64K	596.05
u0-0	RAID-5	OK	-	-	-	64K	-
u0-0-0	DISK	OK	-	-	p0	-	149.10
u0-0-1	DISK	OK	-	-	p2	-	149.10
u0-0-2	DISK	OK	-	-	p3	-	149.10
u0-1	RAID-5	OK	-	-	-	64K	-
u0-1-0	DISK	OK	-	-	p4	-	149.10
u0-1-1	DISK	OK	-	-	p5	-	149.10
u0-1-2	DISK	OK	-	-	p6	-	149.10

```
//localhost> /c0/u1 show
```

Unit	UnitType	Status	%RCmpl	%V/I/M	Port	Stripe	Size(GB)
u1	RAID-0	OK	-	-	-	64K	3576.06
u1-0	DISK	OK	-	-	p0	-	298.01
u1-1	DISK	OK	-	-	p1	-	298.01
u1-2	DISK	OK	-	-	p2	-	298.01
u1-3	DISK	OK	-	-	p3	-	298.01
u1-4	DISK	OK	-	-	p4	-	298.01
u1-5	DISK	OK	-	-	p5	-	298.01
u1-6	DISK	OK	-	-	p6	-	298.01
u1-7	DISK	OK	-	-	p7	-	298.01
u1-8	DISK	OK	-	-	p8	-	298.01
u1-9	DISK	OK	-	-	p9	-	298.01
u1-10	DISK	OK	-	-	p10	-	298.01
u1-11	DISK	OK	-	-	p11	-	298.01
u1/v0	Volume	-	-	-	-	-	2047.00
u1/v1	Volume	-	-	-	-	-	1529.06

## `/cx/ux show attribute [attribute ...]`

This command shows the current setting of the specified attributes. One or many attributes can be requested. Specifying an invalid attribute will terminate the loop. Possible attributes are: `initializestatus`, `name` (9000 series), `qpolicy` (9550SX, 9590SE, and 9650SE only), `rebuildstatus`, `serial` (9000 series), `status`, `storsave` (9550SX, 9590SE, and 9650SE only), `verifystatus`, `volumes` (9000 series), `autoverify` (9000 series), `cache`, `ignoreECC` (9000 series), and `identify` (9550SX, 9590SE, and 9650SE only).

## `/cx/ux show status`

This command reports the status of the specified unit.

Possible statuses include: OK, VERIFYING, VERIFY-PAUSED, INITIALIZING, INIT-PAUSED, REBUILDING, REBUILD-PAUSED, DEGRADED, MIGRATING, MIGRATE-PAUSED, RECOVERY, INOPERABLE, and UNKNOWN. (Definitions of the unit statuses are available in the *3ware Serial ATA RAID Controller User Guide*.)

### **Example:**

```
//localhost> /c0/u0 show status
/c0/u5 status = OK
```

## `/cx/ux show rebuildstatus`

This command reports the rebuildstatus (if any) of the specified unit.

### **Example:**

```
//localhost> /c0/u5 show rebuildstatus
/c0/u5 is not rebuilding, its current state is OK
```

If the unit is in the process of migrating, the command will return the following:

```
//localhost> /c0/u5 show rebuildstatus
/c0/u5 is not rebuilding, its current state is MIGRATING
```

## `/cx/ux show verifystatus`

This command reports the verifystatus (if any) of the specified unit.

### **Example:**

```
//localhost> /c0/u5 show verifystatus
/c0/u5 is not verifying, its current state is OK
```

## /cx/ux show initializestatus

This command reports the initializestatus (if any) of the specified unit.

**Example:**

```
//localhost> /c0/u5 show initializestatus  
/c0/u5 is not initializing, its current state is OK
```

## /cx/ux show name

This feature only applies to 9000 series controllers.

This command reports the name (if any) of the specified unit.

**Example:**

```
//localhost> /c0/u5 show name  
/c0/u5 name = Joe
```

## /cx/ux show serial

This feature only applies to 9000 series controllers.

This command reports the unique serial number of the specified unit.

**Example:**

```
//localhost> /c0/u5 show serial  
/c0/u5 Serial Number = 12345678901234567890
```

## /cx/ux show qpolicy

This feature only applies to 9550SX, 9590SE, and 9650SE model controllers.

This command reports the queue policy of the firmware. If the queue policy is on, the firmware utilizes the drive queueing policy. If some drives in the unit do not support a queueing policy, this policy will have no effect on those drives.

Note that currently only NCQ will be enabled, not tag-queueing.

**Example:**

```
//localhost> /c0/u5 show qpolicy  
/c0/u5 Command Queuing Policy = on
```

## /cx/ux show storsave

This feature only applies to 9550SX, 9590SE, and 9650SE model controllers.

This command reports the storsave policy on the unit.

For more information see, “/cx/ux set storsave=protect|balance|perform [quiet]” on page 70.

**Example:**

```
//localhost> /c0/u5 show storsave
/c0/u5 Command Storsave Policy = protect
```

## /cx/ux show identify

This feature only applies to 9550SX, 9590SE, and 9650SE model controllers.

This command is related to the **/cx/ux set identify** command. It shows the identify status of the specified unit (either on or off).

**Example:**

```
//localhost> /c0/u0 show identify
/c0/u0 Identify status = on
```

## /cx/ux show autoverify

This feature only applies to 9000 series controllers.

This command shows the current autoverify setting of the specified unit.

**Example:**

```
//localhost> /c0/u0 show autoverify
/c0/u0 Auto Verify Policy = off
```

## /cx/ux show cache

This command shows the current write cache state of the specified unit.

**Example:**

```
//localhost> /c0/u0 show cache
/c0/u0 Cache State = on
```

## /cx/ux show ignoreECC

This feature only applies to 9000 series controllers.

This command shows the current setting of the ignoreECC policy for the specified unit.

**Example:**

```
//localhost> /c0/u0 show ignoreECC
/c0/u0 Ignore ECC policy = off
```

## /cx/ux show volumes

This feature only applies to 9000 series controllers.

This command reports the number of volumes in the specified unit. The number of volumes will normally be “1” unless the drive capacity exceeds 2TB and auto-carving is enabled.

**Example:**

```
//localhost> /c0/u0 show volumes
/c0/u0 volume(s) = 1
```

## /cx/ux show all

This command shows the current setting of all above attributes.

If the auto-carve policy was on at the time the unit was created and the unit is over the carve size, multiple volumes were created and are displayed at the end of the summary information. Similarly, if the unit was created using the 3ware BIOS utility 3BM and a size was entered in the Boot Volume Size field, multiple volumes were created and will be displayed. (Note that a volume created using the Boot Volume Size feature does not have to be used as a boot volume.)

**Example:**

```
//localhost> /c0/u1 show all
/c0/u1 status = OK
/c0/u1 is not rebuilding, its current state is OK
/c0/u1 is not verifying, its current state is OK
/c0/u1 is not initializing, its current state is OK
/c0/u1 Cache State = on
/c0/u1 volume(s) = 2
/c0/u1 name = myarray
/c0/u1 serial number = C6CPR7JMF98DA8001DF0
/c0/u1 Ignore ECC policy = on
/c0/u1 Auto Verify Policy = on
```

Unit	UnitType	Status	%RCmpl	%V/I/M	Port	Stripe	Size(GB)
u1	RAID-0	OK	-	-	-	64K	3576.06
u1-0	DISK	OK	-	-	p0	-	298.01
u1-1	DISK	OK	-	-	p1	-	298.01
u1-2	DISK	OK	-	-	p2	-	298.01
u1-3	DISK	OK	-	-	p3	-	298.01
u1-4	DISK	OK	-	-	p4	-	298.01
u1-5	DISK	OK	-	-	p5	-	298.01
u1-6	DISK	OK	-	-	p6	-	298.01
u1-7	DISK	OK	-	-	p7	-	298.01
u1-8	DISK	OK	-	-	p8	-	298.01
u1-9	DISK	OK	-	-	p9	-	298.01
u1-10	DISK	OK	-	-	p10	-	298.01
u1-11	DISK	OK	-	-	p11	-	298.01
u1/v0	Volume	-	-	-	-	-	2047.00
u1/v1	Volume	-	-	-	-	-	1529.06

## /cx/ux remove [noscan] [quiet]

This command allows you to remove (previously called “export”) a unit. Removing a unit instructs the firmware to remove the specified unit from its poll of managed units, but retains the DCB (Disk Configuration Block) metadata. A removed unit can be moved to a different controller.

**noscan** is used to not inform the operating system of this change. The default is to inform the operating system.

**quiet** is used for non-interactive mode. No confirmation is given and the command is executed immediately. This is useful for scripting purposes.

Example of interactive mode:

```
//localhost> /c0/u0 remove
Removing /c0/u0 will take the unit offline.
Do you want to continue?
Y|N [N]:
```



**Note:** After the unit is removed through the CLI, the unit can be physically removed. Hot swap carriers are required to do this while the system is online. Otherwise you must power down the system to prevent system hangs and damage.

## /cx/ux del [noscan] [quiet]

This command allows you to delete a unit. Deleting a unit not only removes the specified unit from the controller's list of managed units, but also destroys the DCB (Disk Configuration Block) metadata. After deleting a unit, ports (or disks) associated with the unit will be part of the free pool of managed disks.



**Warning:** This is a destructive command and should be used with care. All data on the specified unit will be lost after executing this command.

**noscan** is used to not inform the operating system of this change. The default is to inform the operating system.

**quiet** is used for non-interactive mode. No confirmation is given and the command is executed immediately. This is useful for scripting purposes.

Example of interactive mode:

```
//localhost> /c0/u0 del
Deleting /c0/u0 will cause the data on the unit to be
permanently lost.
Do you want to continue ? Y|N [N]:
```

## /cx/ux start rebuild disk=*p*<*p*:-*p*...> [ignoreECC]

This command allows you to rebuild a degraded unit using the specified **disk=*p***. Rebuild only applies to redundant arrays such as RAID 1, RAID 5, RAID 6, RAID 10, and RAID 50.

During rebuild, bad sectors on the source disk will cause the rebuild to fail. RAID 6 arrays are less susceptible to failing since two copies of the data exist. You can allow the operation to continue by using *ignoreECC*.

The rebuild process is a background task and will change the state of a unit to REBUILDING. Various show commands also show the percent completion as rebuilding progresses.

Note that the disk used to rebuild a unit (specified with **disk=*p***) must be a SPARE or a unconfigured disk. You must first remove the degraded drive(s) before starting the rebuild. Refer to the command “/cx/px remove [noscan] [quiet]” on page 81 for details. Also refer to the command “/cx rescan [noscan]” on page 43 to add new drives or to retry the original drive.

If you are rebuilding a RAID 50, RAID 6, or RAID 10 unit, multiple drives can be specified if more than one sub-array is degraded.

When you issue this command, the specified rebuild will begin if schedules are disabled; otherwise it will pause until the next scheduled rebuild. A file system check is recommended following rebuild when using the *ignoreECC* option.



## /cx/ux start verify

This command starts a background verification process on the specified unit **/cx/ux**. The following table shows the supported matrix as a function of the controller model and logical unit type.

N/A (Not Applicable) refers to cases where the given logical unit type is not supported on that controller model.

**Table 9: Supported RAID (Logical Unit) Types for Verification**

Model	R0	R1	R5	R6	R10	R50	Single	JBOD	Spare
7K/8K	No	Yes	Yes	N/A	Yes	N/A	N/A	No	No
9000 <sup>a</sup>	Yes	Yes	Yes	N/A	Yes	Yes	Yes	Yes	Yes
9650SE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes

a. Models 9500S, 9550SX, and 9590SE

When you issue this command, the specified verify will begin if schedules are disabled; otherwise it will pause until the next scheduled verify. Verify will also pause if a rebuild or initialization is currently in progress.

## /cx/ux pause rebuild

This command allows you to pause the rebuild operation on the specified unit **/cx/ux**.

This feature is only supported on the 7000/8000 series controllers. 9000 series controllers have an on-board scheduler where rebuild operations can be scheduled to take place at specified start and stop times. The **/cx/ux pause rebuild** command is provided to enable 7000/8000 users to achieve similar functionality with use of Linux-provided schedulers such as cron(8) or at(1), or user-supplied programs.

## /cx/ux resume rebuild

This command allows you to resume the rebuild operation on the specified unit **/cx/ux**.

This feature is intended only for 7000/8000 series controllers. 9000 series controllers have an on-board scheduler where rebuild operations can be scheduled to take place at specified start and stop times. The **/cx/ux resume rebuild** function is provided to enable 7000/8000 users to achieve similar

functionality with use of Linux-provided schedulers such as cron(8) or at(1), or user supplied programs.

## `/cx/ux stop verify`

This command stops a background verification process on the specified unit `/cx/ux`. Table 9 on page 67 shows the supported matrix as a function of the controller model and logical unit type.

## `/cx/ux flush`

This command allows you to flush the write cache on the specified unit `/ux` associated with controller `/cx`. Note that this command does not apply to spare unit types.

## `/cx/ux set autoverify=on|off`

This feature only applies to 9000 series controllers.

This command allows you to turn on and off the autoverify operation on a specified unit `/cx/ux` during allocated schedule windows.

You can use the **show verify** command to display the existing schedule windows. By default, autoverify is **off**.

Auto-verify allows the controller to run the verify function once every 24 hours. If verify schedule windows are set up and enabled, then the controller will only start an automatic verify task during the schedule time slots. If the verify takes longer than the schedule window, the verify process will be paused and restarted during the next verify schedule window. For additional information, see “Setting Up a Verify Schedule” on page 51.

## `/cx/ux set cache=on|off [quiet]`

This command allows you to turn **on** or **off** the write cache for a specified unit `/cx/ux`. This feature is supported on both 7000/8000 and 9000 models.

By default, cache is **on**.

Write cache includes the disk drive cache and controller cache. Note that for some configuration types, there is only disk drive cache and no controller cache (for example, JBOD).

The following table shows the supported RAID types for caching as a function of controller model and logical unit type. N/A (Not Applicable) refers to cases where the given logical unit type is not supported on a particular controller model.

**Table 10: Supported RAID Types for Caching**

Model	R0	R1	R5	R6	R10	R50	Single	JBOD	Spare
7K/8K	Yes	Yes	Yes	N/A	Yes	N/A	N/A	Yes	No
9000 <sup>a</sup>	Yes	Yes	Yes	N/A	Yes	Yes	Yes	Yes	No
9650SE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	No

a. Models 9500S, 9550SX, and 9590SE

The **quiet** attribute turns off interactive mode.

## /cx/ux set identify=on|off

This feature only applies to 9550SX, 9590SE, and 9650SE model controllers.

This feature requires an enclosure that uses an integrated AMCC/3ware CCU (chassis control unit). (Check the 3ware web site for a list of chassis vendors that support enclosure services, as they become available.) For additional information about enclosure-related commands, see “Enclosure Object Commands” on page 87.

This command allows you to identify a unit within an enclosure by blinking the LEDs associated with the drive slots of the specified unit.

### Example:

```
//localhost> /c0/u0 set identify=on
Sending Identify request for unit /c0/u0 to [on] ... Done.
```

## /cx/ux set ignoreECC=on|off

This feature only applies to 9000 series controllers.

This command allows you to set the ignoreECC policy for a given unit.

When ignoreECC policy is set to **off**, if a rebuild process encounters bad sectors on the source disk, the rebuild will fail. When ignoreECC is set to **on**, such errors are ignored, and the rebuild will continue. When you use ignoreECC, a file system check is recommended following the rebuild, to insure data integrity.

By default, ignoreECC is **off**.

See Table 8, “Supported Model-Unit Types for ignoreECC,” on page 42

## `/cx/ux set name=string`

This command allows you to name the unit with an arbitrary name. You can use this name in conjunction with the unit serial number to cross-reference with the unit. The system does not check to ensure uniqueness of names, so be careful to assign different names to each unit.



**Note:** The unit's serial number is automatically assigned when the unit is created and is not changeable.

## `/cx/ux set qpolicy=on|off`

This command applies only to 9550SX, 9590SE, and 9650SE controllers.

This command sets the queue policy of the firmware. If the queue policy is **on**, the firmware utilizes the drive queuing policy. If some of the drives in the unit do not support any queuing policy, this policy will have no effect on those drives.

By default, qpolicy is **on**.

**Example:**

```
//localhost> /c0/u5 set qpolicy = on
Setting Command Queuing Policy for unit /c0/u5 to [on] ... Done.
```

## `/cx/ux set storsave=protect|balance|perform [quiet]`

This command applies only to 9550SX, 9590SE, and 9650SE model controllers.

This command sets the storsave policy to be either **protect**, **balance**, or **perform** when the unit write cache is enabled. The default setting is **protect**.

The storsave policy adjusts several factors that control the balance between protection and performance on a unit. There is a trade-off among the available settings. The following description about the settings should help you to decide which one is suitable to you and your application. You will find further discussion of this setting in the *3ware Serial ATA RAID Controller User Guide*, under “About StorSave Profile Levels” on page 117.

**protect** provides the maximum data protection among the controller settings. When storsave is set to **protect** mode, it means:

- When the unit becomes degraded, the write cache will be disabled.
- Write journaling is enabled. All data flushing from controller cache will be flushed to media.
- Incoming FUA (Force Unit Access) host requests will be honored unless a BBU is installed and enabled, in which case, they will be ignored.

**perform** provides the maximum performance and least data protection of the three controller settings. When storsave is set to **perform** mode, it means:

- When the unit becomes degraded, the write cache will not be disabled.
- Write journaling is disabled. All data flushing from controller cache will be flushed to disk. If a BBU is present, this essentially disables the BBU for this unit.
- Incoming FUA (Force Unit Access) host requests will be honored.

If you set the storsave policy to **perform**, a confirmation message will warn you that there could be data loss in the event of a power failure.

**balance** provides more data protection than perform mode but less data protection than protect mode, and provides better performance than protect mode but less performance than perform mode. When storsave is set to the **balance** mode, it means:

- When the unit becomes degraded, the write cache will not be disabled.
- Write journaling is disabled, if no BBU is present, and is enabled, if a BBU is present. All data flushing from controller cache will be flushed to media if a BBU is installed and enabled. Otherwise, data will be flushed to disk only.
- Incoming FUA (Force Unit Access) host requests will be honored unless a BBU is installed and enabled, in which case, they will be ignored.

**quiet** is used for non-interactive mode. No confirmation is given and the command is executed immediately. This is useful for scripting purposes.

For additional information, see “Setting the StorSave Profile for a Unit” in the *3ware Serial ATA RAID Controller User Guide*.

**Example:**

```
//localhost> /c0/u5 set storsave=protect
Setting Command Storsave Policy for unit /c0/u5 to [protect] ...
Done.
```

```
/cx/ux migrate type=RaidType [disk=p:-p]
[group=3|4|5|6|7|8] [stripe=Stripe] [noscan]
[nocache] [autoverify]
```

This feature only applies to 9000 series controllers.

This command allows you to change the existing configuration of a unit with **type=*RaidType***. You can make three types of changes:

- Increase the capacity
- Change the RAID level (with the same or increased capacity)
- Change the stripe size

The unit that results from the migration is subject to the same rules and policies that apply when creating a new unit with the **/cx add** command. For example, a valid number of disks and parameters must be specified.

The unit to be migrated must be in a normal state (not degraded, initializing, or rebuilding) before starting the migration.

The destination unit must use all source disks and potentially augment the number of disks in the **disk=*p*:-*p*** disk list. Unspecified parameters are assigned the default values (stripe size of 64K, write cache enabled, autoverify disabled, and ignoreECC disabled). Both source name and serial number will be carried over to the destination unit.

A special case of this command is when the source unit has a type of RAID1 and destination unit has a type of single. In this case, the migrate command splits both drives into two identical single disks. The disk name will be duplicated on the destination units, but the source unit serial number will not be carried over to the new unit. The new destination unit will have its own serial number.

**type=*RaidType*** specifies the RAID type of the destination unit. Possible unit types include **raid0**, **raid1**, **raid5**, **raid6**, **raid10**, **raid50**, or **single**.

For example, **type=raid5** indicates the destination unit is RAID-5. The **type=single** is a special case of the migrate command. It splits the source unit RAID-1 or TWINSTOR into multiple Single units.



**Note:** You can only migrate a unit to a RAID level that has the same or more capacity as the existing one. A four-drive RAID 5 unit can migrate to a four-drive RAID 0, but a four-drive RAID 0 unit cannot migrate to a four-drive RAID 5, without adding another drive, due to the need for additional storage capacity for parity bits.

The following table illustrates valid migration paths:

**Table 11: Valid Migration Paths**

Source	Destination								
	R0	R1	R5	R6	R10	R50	Single	JBOD	Spare
<b>R0</b>	Yes	No	Yes	Yes	Yes	Yes	No	No	No
<b>R1</b>	Yes	No	Yes	Yes	Yes	Yes	Yes	No	No
<b>R5</b>	Yes	No	Yes	Yes	Yes	Yes	No	No	No
<b>R6</b>	Yes	No	Yes	Yes	Yes	Yes	No	No	No
<b>R10</b>	Yes	No	Yes	Yes	Yes	Yes	No	No	No
<b>R50</b>	Yes	No	Yes	Yes	Yes	Yes	No	No	No
<b>Single</b>	Yes	Yes	Yes	Yes	Yes	Yes	No	No	No
<b>JBOD</b>	No	No	No	No	No	No	No	No	No
<b>Spare</b>	No	No	No	No	No	No	No	No	No

**disk=*p*:-*p*..** consists of a list of ports (disks) to be used in addition to the source disks in the construction of the destination unit. One or more ports can be specified. Multiple ports can be specified using a colon (: ) or a dash (-) as port index separators. A dash indicates a range and can be mixed with colons. For example **disk=0:1:2-5:9:12** indicates port 0, 1, 2 through 5 (inclusive), 9 and 12.

**group=3/4/5/6/7/8** indicates the number of disks per group for a RAID 50 type. (This attribute can only be used when type=raid50.) Recall that a RAID 50 is a multi-tier array. At the bottom-most layer, N number of disks per group are used to form the RAID 5 layer. These RAID 5 arrays are then integrated into a RAID 0. This attribute allows you to specify the number of disks in the RAID 5 level. Valid values are 3, 4, 5, 6, 7, and 8. For example **group=3** indicates 3 disks of RAID 5 at the bottom layer of RAID 50.

Note that a sufficient number of disks are required for a given pattern or disk group. For example, given 6 disks, specifying 3 will create two RAID 5 arrays. With 12 disks, specifying 3 will create four RAID 5 arrays under the RAID 0 level. With only 6 disks a grouping of 6 is not allowed, as you would basically be creating a RAID 5.

The default RAID 50 grouping varies, based on number of disks. For 6 and 9 disks, default grouping is 3. For 8 disks, the default grouping is 4. For 10 disks, the default grouping is 5, and for 12 disks, the disks can be grouped into groups of 3, 4, or 6 drives (the group of 4 drives is set by default as it provides

the best of net capacity and performance). For 15 disks, the disks can be grouped into groups of 3 or 5 drives. For 16 disks, the disks can be grouped into groups of 4 or 8 drives.

Note that RAID-10 always has **group=2**, so an attribute specifying it's group is not necessary.

**stripe=Stripe** consists of the stripe size to be used. The following table illustrates the supported and applicable stripes on unit types and controller models. Stripe size units are in KB (kilobytes).

**Table 12: Supported Stripe Sizes**

Model	R0	R1	R5	R6	R10	JBOD	Spare	R50	Single
7/8000	64	N/A	64	N/S	64	N/A	N/A	N/S	N/S
	128				128				
	256				256				
	512				512				
	1024				1024				
9000 <sup>a</sup>	16	N/A	16	N/S	16	N/A	N/A	16	N/S
	64		64	N/S	64			64	
	256		256	N/S	256			256	
9650SE	16	N/A	16		16	N/A	N/A	16	N/S
	64		64	64	64			64	
	256		256		256			256	

a. Models 9500S, 9550SX, and 9590SE

**noscan** attribute instructs CLI not to notify the operating system of the creation of the new unit. By default CLI will inform the operating system. One application of this feature is to prevent the operating system from creating block special devices such as /dev/sdb and /dev/sdc as some implementations might create naming fragmentation and a moving target.

**nocache** attribute instructs CLI to disable the write cache on the migrated unit. Enabling write cache increases write performance at the cost of potential data loss in case of sudden power loss (unless a BBU or UPS is installed). By default the cache is enabled. To avoid the possibility of data loss in the event of a sudden power loss, it is recommended not to set nocache unless there is a BBU (battery backup unit) or UPS (uninterruptibleuninterruptible power supply) installed..



**autoverify** attribute enables the autoverify attribute on the unit that is to be migrated. For more details on this feature, see “/cx/ux set autoverify=on|off” on page 68.

## Migration Process

In all cases of migration, the background migration process must be completed before the newly sized unit is available for use. You can continue using the original unit during this time. Once the migration is finished, a reboot will be required if you are booted from the unit. For secondary storage, depending on your operating system, you may need to first unmount the unit, then use CLI commands to ‘remove’ and ‘rescan’ the unit so that the operating system can see the new capacity, and then remount the unit. For details see “/cx/ux remove [noscan] [quiet]” on page 65 and “/cx rescan [noscan]” on page 43.

You may also need to resize the file system or add a new partition. For instructions, consult the documentation for your operating system.



**Warning:** It is important that you allow migration to complete before adding drives to the unit. Making physical changes to the unit during migration may cause the migration process to stop, and can jeopardize the safety of your data.

## Example of splitting a mirror

```
//localhost> /c1/u3 migrate type=single
```

Indicates that u3 should be split into Single units. In this case, u3 is a RAID-1 and the Migrate command splits u3 into u3 and ux, each with a RAID type of Single.



**Warning:** Make sure that no I/O is pending before splitting a mirror. If the Raid 1 is the boot device, you should boot from a different device before splitting the mirror.

## Example of capacity expansion

```
//localhost> /c0/u3 migrate type=raid10 disk=10-11 stripe=16
```

Indicates that the destination unit has a RAID type of raid10 and has added the disks 10 and 11 to the disks in the existing unit u3.

## Example of migrate output

The following is an example of how migrating units will be displayed. In this example, the report indicates that /c0/u3 is a migrating unit with 39% completion. The report also indicate that Source Unit su0 is of type RAID-1 and Destination Unit du0 is of type RAID-10.

```
3ware CLI> /c0 show
```

Unit	UnitType	Status	%RCmpl	%V/I/M	Stripe	Size(GB)	Cache	AVrfy
u0	RAID-5	OK	-	-	64K	596.004	ON	OFF
u2	SPARE	OK	-	-	-	149.042	-	OFF
u3	Migrator	MIGRATING	-	39	-	149.001	ON	OFF

Port	Status	Unit	Size	Blocks	Serial
p0	OK	u0	149.05 GB	312581808	WD-WCANM1771318
p1	OK	u0	149.05 GB	312581808	WD-WCANM1757592
p2	OK	u0	149.05 GB	312581808	WD-WCANM1782201
p3	OK	u0	149.05 GB	312581808	WD-WCANM1753998
p4	OK	u2	149.05 GB	312581808	WD-WCANM1766952
p5	OK	u3	149.05 GB	312581808	WD-WCANM1882472
p6	OK	u0	149.05 GB	312581808	WD-WCANM1883862
p7	OK	u3	149.05 GB	312581808	WD-WCANM1778008
p8	OK	-	149.05 GB	312581808	WD-WCANM1770998
p9	NOT-PRESENT	-	-	-	-
p10	OK	u3	149.05 GB	312581808	WD-WCANM1869003
p11	OK	u3	149.05 GB	312581808	WD-WCANM1762464

```
3ware CLI> /c0/u0 show
```

Unit	UnitType	Status	%RCmpl	%V/I/M	Port	Stripe	Size(GB)
u3	Migrator	MIGRATING	-	39	-	-	-
su3	RAID-1	OK	-	-	-	-	149.001
su3-0	DISK	OK	-	-	p5	-	149.001
su3-1	DISK	OK	-	-	p7	-	149.001
su3/v0	Volume	-	-	-	-	-	149.001
du3	RAID-10	OK	-	-	-	16K	298.002
du3-0	RAID-1	OK	-	-	-	-	-
du3-0-0	DISK	OK	-	-	p5	-	149.001
du3-0-1	DISK	OK	-	-	p7	-	149.001
du3-1	RAID-1	OK	-	-	-	-	-
du3-1-0	DISK	OK	-	-	p10	-	149.001
du3-1-1	DISK	OK	-	-	p11	-	149.001
du3/v0	Volume	-	-	-	-	-	149.001

## Port Object Commands

Port Object Messages are commands that provide information and perform actions related to a specific disk, attached to a port, such as **/c0/p0**. You use port object commands for such tasks as seeing the status, model, or serial number of the drive.

### Syntax

```
/cx/px show
/cx/px show attribute [attribute ...] where attributes are:
    capacity|firmware|identify (9550SX, 9590SE, 9650SE)|
    lspeed (9550SX, 9590SE, 9650SE)|model|
    ncq (9550SX, 9590SE, 9650SE)|serial|smart|status
/cx/px show all

/cx/px remove [noscan][quiet]
/cx/px set identify=on|off (9550SX, 9590SE, 9650SE)
```

### /cx/px show

This command shows summary information about the specified disk attached to port **/cx/px**. Typical information looks like:

#### Example:

```
//localhost> /c1/p5 show
```

Port	Status	Unit	Size	Blocks	Serial
p5	OK	u0	149.05 GB	312581808	3JS0L9QW

The above report indicates that port 5 of controller 1 is attached to one 1 disk with status OK participating in unit 0.

### /cx/px show *attribute [attribute ...]*

This command shows the current setting of the given attributes on the specified port or drive. One or many attributes can be requested. Specifying an invalid attribute will terminate the loop. Possible attributes are: capacity, firmware, identify (9550SX, 9590SE, and 9650SE only), lspeed (9550SX, 9590SE, and 9650SE only), model, ncq (9550SX, 9590SE, and 9650SE only), serial, smart, and status.

## /cx/px show status

This command displays the status of the drive attached to the specified port. (Definitions of the drive statuses are available in the *3ware Serial ATA RAID Controller User Guide*.)

**Example:**

```
//localhost> /c0/p5 show status
/c0/p5 Status = OK
```

## /cx/px show model

This command displays the model of the drive attached to the specified port.

**Example:**

```
//localhost> /c0/p5 show model
/c0/p5 Model = WDC WD1600BB-00DAA0
```

## /cx/px show serial

This command displays the serial number of the drive attached to the specified port.

**Example:**

```
//localhost> /c0/p5 show serial
/c0/p5 Serial = WD-WMACK140649
```

## /cx/px show firmware

This command displays the firmware version of the drive attached to the specified port.

**Example:**

```
//localhost> /c0/p5 show firmware
/c0/p5 Firmware Version = 65.13G65
```

## /cx/px show identify

This command applies only to 9550SX, 9590SE, and 9650SE model controllers that have chassis control hardware (enclosure services) attached.

This command shows whether the LED of the drive attached to the specified port is set to **on** or **off**. For details, see “/cx/px set identify=on|off” on page 81.

**Example:**

```
//localhost> /c0/p5 show identify
/c0/p5 Identify Status = on
```

## /cx/px show ncq

This command applies only to 9550SX, 9590SE, and 9650SE model controllers.

This command displays the NCQ (Native Command Queuing) information for the drive attached to the specified port, including whether NCQ is supported by the drive, and whether it is enabled at the drive.

For queuing to be used, it must be enabled for the unit and supported by the drive.

**Example:**

```
//localhost> /c0/p5 show ncq
/c0/p5 NCQ Supported = No
/c0/p5 NCQ Enabled = No
```

## /cx/px show lspeed

This command applies only to 9550SX, 9590SE, and 9650SE model controllers.

This command displays the maximum SATA link speed supported by the drive attached to the port and the present SATA link speed setting.

**Example:**

```
//localhost> /c0/p5 show lspeed
/c0/p5 SATA Link Speed Supported = 3.0 Gb/s
/c0/p5 SATA Link Speed = 3.0 Gb/s
```

## /cx/px show capacity

This command displays the capacity of the drive attached to the specified port in two formats—GB and blocks. Note that of this version, the GB format is computed based on division by 1000 (not 1024).

**Example:**

```
//localhost> /c0/p5 show capacity
149.05 GB (312581808 Blocks)
```

## /cx/px show smart

This command extracts SMART (Self Monitoring Analysis and Reporting) data from the specified disk. Because the data is extracted live from the disk, this command can be used to get the most recent data about the presence or absence of a disk.

The SMART data is displayed in hexadecimal form.

**Example:**

```
//localhost> /c0/p5 show smart
/c0/p5 Drive SMART Data:
10 00 01 0B 00 C8 C8 00 00 00 00 00 00 03 07
00 9A 96 BC 14 00 00 00 00 04 32 00 64 64 7A
00 00 00 00 00 00 05 33 00 C8 C8 00 00 00 00 00
...
00 00 00 00 00 00 00 00 00 00 00 00 00 00 2C
```



**Note:** The SMART data is not decoded. If the drive attached to the specified port is not present or if there are cabling problems reaching the drive, CLI will return an error. This can be one way of detecting whether or not a drive is present.

## /cx/p $x$ show all

This command shows the current setting for all port-related attributes: status, model, serial, firmware, capacity, and smart.

**Example:**

```
//localhost> /c0/p0 show all
/c0/p0 Status = OK
/c0/p0 Model = Maxtor 7B300S0
/c0/p0 Firmware Version = BANC1980
/c0/p0 Serial = B605X31H
/c0/p0 Capacity = 279.48 GB (586114704 Blocks)
/c0/p0 Identify Status - NA
/c0/p0 SATA Link Speed Supported = 1.5 Gb/s
/c0/p0 SATA Link Speed = 1.5 Gb/s
/c0/p0 NCQ Supported = No
/c0/p0 NCQ Enabled = No
/c0/p0 Belongs to Unit = u1

/c0/p0 Drive Smart Data:
0A 00 01 0F 00 3D 33 25 8C BA 03 00 00 00 03 03
00 61 60 00 00 00 00 00 00 00 04 32 00 64 64 00
00 00 00 00 00 00 05 33 00 64 64 00 00 00 00 00
00 00 07 0F 00 4E 3E 05 13 D8 03 00 00 00 09 32
...
00 00 00 00 00 00 00 00 00 00 00 00 00 00 8D
```

## /cx/px remove [noscan] [quiet]

This command allows you to remove (or export) a port (or drive) **/cx/px**. Exporting a port instructs the firmware to remove the specified port from its pool of managed ports, but does not retain the DCB (Disk Configuration Block) metadata on the attached disk. You can import (or re-introduce) the port by rescanning the controller.

**noscan** is used to not inform the operating system of this change. The default is to inform the operating system.

**quiet** is for non-interactive mode.



**Warning:** Use caution when using this command as this operation will degrade any redundant units. This command will fail if you attempt to remove a drive from a non-redundant unit. After the drive is removed in CLI it can be removed physically, without powering down the system if a hot swap carrier is available. System hangs and damage can occur if a hot swap carrier is not used.

## /cx/px set identify=on|off

This command applies only to 9550SX, 9590SE, and 9650SE model controllers.

This command sets the LED status of the port to **on** or **off**. If identify is set to **on**, the firmware activates the setting of the corresponding LED of the port on the controller and causes it to blink.

**Note:** This command is equivalent to “/ex/slotx set identify=on|off” on page 90.



**Note:** This feature requires an enclosure that uses an integrated AMCC/3ware CCU (chassis control unit). (Check the 3ware web site for a list of chassis vendors that support enclosure services, as they become available.) For additional information about enclosure-related commands, see “Enclosure Object Commands” on page 87.

### Example:

```
//localhost> /c0/p5 set identify=on
Setting Port Identify on /c0/p5 to [on] ... Done.
```

## BBU Object Commands

BBU (Battery Backup Unit) Object Commands are commands that provide information and perform actions related to a specific BBU installed on a specific controller, such as **/c0/bbu**.

This object is only available on 9000 series controllers on which a BBU is actually installed. (The BBU is not supported on 9590SE-4ME.)

### Syntax

```
/cx/bbu show (9000 only)
/cx/bbu show attribute [attribute ...] where attributes are:
    batinst|bootloader|cap|fw|lasttest|pcb|ready|serial|
    status|temp|volt
/cx/bbu show all (9000 only)

/cx/bbu test [quiet] (9000 only)
    Warning: May take up to 24 hours to complete. Write cache
    will be disabled during the test.
/cx/bbu enable (9000 only)
/cx/bbu disable [quiet] (9000 only)
```

### /cx/bbu show

This command presents a summary report on the specified BBU object.

#### Example:

```
//localhost> /c0/bbu show
Name OnlineState BBUReady Status Volt Temp Hours LastCapTest
-----
bbu ON No Testing OK OK 72 01-Jul-2004
```

The command output indicates that the battery capacity was last measured on 01-Jul-2004. The battery is estimated to last for 72 hours from the last tested date. In this example, the BBU unit is currently testing the battery. Both voltage and temperature are normal. The BBU is not ready to backup the write cache on the controller (due to the testing). (For complete information about the BBU, see the user guide that came with your 3ware RAID controller).



**Note:** If the BBU is either not present or disabled, the following will be displayed after the command **//localhost> /c0/bbu show**.

Error: (CLI:053) Battery Backup Unit is not present.



## /cx/bbu show *attribute* [*attribute* ...]

This command shows the current setting of the given attribute(s) on the BBU board. One or many attributes can be specified. Specifying an invalid attribute will terminate the loop. Possible attributes are: batinst, bootloader, cap, fw, lasttest, pcb, ready, status, serial, temp, volt.

## /cx/bbu show status

This command shows the status of the BBU. Possible values are:

**Testing.** A battery test is currently in progress. This test may take up to 24 hours to complete. During the test, the BBU is **not** capable of backup operation and the write cache of the RAID controller is also disabled. If the test is completed with no error and the BBU status changes to WeakBat or OK, the write cache will be re-enabled. If a Fault, Failed or Error occurs during the test, the write cache remains in the disabled state until the problem is fixed.

**Charging.** The BBU is currently charging the battery. Charging is started automatically by the BBU whenever necessary. During charging, the BBU is not capable of backup operation and the write cache is disabled. Once the test is completed with no error and the BBU status changes to OK, the write cache will be re-enabled. If a FAULT or ERROR occurs during the test, the write cache remains in the disabled state until the problem is fixed.

**Fault.** A battery fault is detected. The BBU is not capable of backup operation and the write cache is disabled. Replace the battery and/or the BBU board as soon as possible so that the write cache will be enabled again.

**Error.** A BBU error is detected. The BBU is not capable of backup operation and the write cache is disabled. Replace the battery and/or the Battery Backup Unit as soon as possible so that the write cache will be enabled again.

**Failed.** The battery failed a test. In this state, the BBU is not capable of backup operation and the write cache is disabled. We recommend you replace the battery and/or the Battery Backup Unit as soon as possible so that the write cache will be enabled again.

**WeakBat.** The BBU is functioning normally and is online and capable of backing up the write cache. However, the battery is weak and should be replaced.

**OK.** The BBU is ready, online and capable of backing up the write cache.

- (dash) A battery is not present or a Battery Backup Unit is not installed

## /cx/bbu show batinst

This command **shows** the date when the current battery was installed.

## /cx/bbu show lasttest

This command **shows** the date the battery capacity was last measured. If the battery capacity test has never been run, then 'xx-xxx-xxxx' will be displayed.



**Note:** The estimated BBU capacity hours displayed is based on the measurement taken during the last test. If you have not run the BBU test command for some time, this number can be misleading. For information about running a test, see “/cx/bbu test [quiet]” on page 86.

## /cx/bbu show volt

This command shows the voltage status of the battery. The status can be OK, HIGH, LOW, TOO-HIGH, and TOO-LOW. The HIGH and LOW are in warning range. TOO-HIGH and TOO-LOW are out of the operating range and indicate that it is time to replace the battery. (Contact AMCC to obtain a replacement battery.)

## /cx/bbu show temp

This command **shows** the temperature status of the battery. The status can be OK, HIGH, LOW, TOO-HIGH, and TOO-LOW. The HIGH and LOW are in warning range. TOO-HIGH and TOO-LOW are out of the operating range and indicate that it may be time to replace the battery. (Contact AMCC to obtain a replacement battery.)

## /cx/bbu show cap

This command **shows** the battery capacity in hours.

A value of '0 hours' will be displayed if the battery capacity test has never been run.



**Note:** The estimated BBU capacity hours displayed is based on the measurement taken during the last test. If you have not run the BBU test command for some time, this number can be misleading. You can use the command **/cx/bbu show lasttest** to check the date of the last test. For information about running a test, see “/cx/bbu test [quiet]” on page 86.

## /cx/bbu show serial

This command **shows** the BBU serial number.

## /cx/bbu show fw

This command **shows** the BBU firmware version number.

## /cx/bbu show pcb

This command **shows** the PCB revision number on the BBU.

## /cx/bbu show bootloader

This command **shows** the BBU's boot loader version.

## /cx/bbu show all

This command shows the current settings of all BBU-related attributes: ready, status, batinst, lasttest, volt, temp, cap, serial, fw, pcb, bootloader.

**Example:**

```
//localhost> /c1/bbu show all
/c1/bbu Firmware Version          = BBU: 1.04.00.007
/c1/bbu Serial Number             = Engineering Sample.
/c1/bbu BBU Ready                  = Yes
/c1/bbu BBU Status                 = OK
/c1/bbu Battery Voltage           = OK
/c1/bbu Battery Temperature       = OK
/c1/bbu Estimated Backup Capacity = 241 Hours
/c1/bbu Last Capacity Test        = 22-Jun-2004
/c1/bbu Battery Installation Date = 20-Jun-2004
/c1/bbu Bootloader Version        = BBU 0.02.00.002
/c1/bbu PCB Revision              = 65
//localhost>
```

## `/cx/bbu test [quiet]`

This command starts the battery capacity test. The test may take up to 24 hours to complete. During the test, the BBU is not capable of backup operation and the write cache of all units attached to that controller is disabled. Once the test is completed with no error and the BBU status returns to OK, the write cache will be re-enabled.



**Note:** Once started, the test can not be terminated before it completes. Write cache cannot be enabled until the test completes.

AEN (Asynchronous Event Notification) messages are also generated by controllers to notify the user of the command status.

Check for AENs with the alarms command `/cx show alarms [reverse]`. Using the “reverse” attribute displays the most recent AEN message at the bottom of the list. (For a list of all AENs, see the user guide that came with your 3ware RAID controller.)

## `/cx/bbu enable`

This command enables BBU detection on the controller. If the BBU is Ready, the controller will utilize BBU functionality in the event of a power failure.

## `/cx/bbu disable [quiet]`

This command disables BBU detection on the controller. When disabled, the controller ignores the existence of the BBU and will show no BBU is installed even if a BBU is physically attached.

# Enclosure Object Commands

Enclosure object commands provide information and perform actions related to a specific enclosure, such as **/e0** and its elements, such as **/e0/slot0**. Enclosure object elements include slot, fan, and temperature sensor elements.

These commands are supported on the 9550SX, 9590SE, and 9650SE controllers, when an appropriate enclosure is used. The enclosure must use an integrated AMCC/3ware CCU (chassis control unit). (Check the 3ware web site for a list of chassis vendors that support enclosure services, as they become available.) If you purchased an enclosure directly from a third-party vendor, the appropriate EPCT (Enclosure Port Configuration Table) must have been downloaded to the controller in order to take advantage of these commands.



**Note.** Not all enclosure features may be available on enclosures that use an integrated AMCC/3ware CCU.

## Syntax

```

/ex show (9550SX, 9590SE, 9650SE only)
/ex show attribute [attribute ...] where attributes are:
    controllers|slots|fans|temp
/ex show all (9550SX, 9590SE, 9650SE only)

/ex/slotx show (9550SX, 9590SE, 9650SE only)
/ex/slotx show identify (9550SX, 9590SE, 9650SE only)
/ex/slotx set identify=on|off (9550SX, 9590SE, 9650SE only)

/ex/fanx show (9550SX, 9590SE, 9650SE only)
/ex/tempx show (9550SX, 9590SE, 9650SE only)

```

## /ex show

This command shows summary information on the specified enclosure **/ex**. This report consists of four parts; the **Enclosure** summary listing the present elements, a **Fan** summary section listing of all present fans, a **Temperature Sensor** summary section listing of all present temperature sensors and a **Slot** summary section listing of slots and associated information for the specified enclosure.

Typical output looks like:

```
//localhost> /e0 show
```

```
Encl          Controllers
-----
e0            /c0
```

```
Fan           Status
-----
fan0          OK
```

```
TempSensor    Temperature
-----
temp0         24~C(75~F)
```

```
Slot          Status          Port          Identify
-----
slot0         OK                /c0/p0        No
slot1         OK                /c0/p1        Yes
slot2         NO-DEVICE         -             No
slot3         NO-DEVICE         -             No
```

## */ex show attribute [attribute ...]*

This command shows the current setting of the given attribute(s). One or many attributes can be requested. An invalid attribute will terminate the loop. Possible attributes are: controllers, protocol, slots, fans, and temp.

## */ex show controllers*

This command lists the controller associated with enclosure */ex*.

**Example:**

```
//localhost> /e0 show controllers
/e0 Connected to /c0 controller.
```

## /ex show slots

This command reports the slots in enclosure **/ex** and their associated information.

**Example:**

```
//localhost> /e0 show slots
```

Slot	Status	Port	Identify
slot0	OK	/c0/p0	No
slot1	OK	/c0/p1	Yes
slot2	NO-DEVICE	-	No
slot3	NO-DEVICE	-	No

## /ex show fans

This command lists the fans in enclosure **/ex** and shows their status. Possible statuses are OK and Unknown.

**Example:**

```
//localhost> /e0 show fans
```

Fan	Status
fan0	OK

## /ex show temp

This command lists the temperature sensors in enclosure **/ex** and the current temperature.

The maximum temperature for successful use of a drive should be noted in the documentation for the drive.

**Example:**

```
//localhost> /e0 show temp
```

TempSensor	Temperature
temp0	24~C(75~F)

## /ex show all

This command shows the current settings of all attributes for enclosure **/ex**.

## /ex/slotx show

This command shows information about the specified **/slotx** on the specified enclosure **/ex**. The slot name is followed by its status. If a slot has been inserted with a drive and no fault has been detected, the status is **OK**. If the slot is empty the status would indicate **NO-DEVICE**. The port that is correlated to the slot is indicated in the next column. If no device is found in the slot, that is indicated with a dash (-) in the Port column. The final column shows whether “identify” is currently set for the specified slot.

**Example:**

```
//localhost> /e0/slot1 show
Slot      Status      Port      Identify
-----
slot1     OK          /c0/p1    Yes
```

## /ex/slotx show identify

This command shows the identify status of the specified slot. The status can be either **on** or **off**.

**Example:**

```
//localhost> /e0/slot1 show identify
/e0/slot1 Identify status = on
```

## /ex/slotx set identify=on|off

This command causes the slot to be identified by blinking the LED associated with it, or turns off identification of the LED for this slot.

Setting identify to **on** will cause the LED associated with that slot to blink, provided that the EPCT has been set to associate “identify” with “blinking,” as is the case in the 3ware Sidecar.

**Note:** This command is equivalent to “/cx/px set identify=on|off” on page 81.

**Example:**

```
//localhost> /e0/slot1 set identify=on
Sending Identify request to Drive Slot /e0/slot0 to [on] ...
Done.
```



## /ex/fanx show

This command shows the information about the specified fan element **/fanx** in the specified enclosure **/ex**. The fan name is followed by its status. If a fan is on and no fault has been detected, the status would indicate OK.

**Example:**

```
//localhost> /e0/fan0 show
Fan          Status
-----
fan0         OK
```

## /ex/tempx show

This command shows the information about the specified temperature sensor element **/fanx** in the specified enclosure **/ex**. The temperature sensor name is followed by the temperature sensed in the enclosure unit.

**Example:**

```
//localhost> /e0/temp0 show
TempSensor   Temperature
-----
temp0        24~C(75~F)
```

## Help Commands

The Help commands provides brief on-line help.

You can get overview help by typing Help at the top-level prompt. This displays a brief definition of commands. (For an example, see the discussion of the command “help” on page 93.)

You can also get help with specific commands, by entering *help* before an object name, or by typing a question mark (?) at the point in a command where you are uncertain what the attributes are.

## Help with specific commands

If you enter the help command at the top level, you are considered to be in the Shell Object, and the help command will provide help on the Shell commands focus, show, flush, rescan, and commit. Using the help command on objects (such as **/cx**, **/cx/ux**, **/cx/px**, **/cx/bbu**, **/ex**, **/ex/slotx**, **/ex/fanx**, and **/ex/tempx**), displays all possible sub-commands associated with the object.

For example: help on the controller object **/cx**, will display all the sub-commands associated with the controller **/cx**, like this:

```

//localhost> help /cx
/cx show
/cx show attribute [attribute ...] where attribute is:
    achip|allunitstatus|autocarve|autorebuild (9550SX,
    9590SE, 9650SE only)|bios|carvesize(9000 series)|
    ctlbus (9550SX, 9590SE, 9650SE)|driver|drivestatus|
    exportjbod|firmware|memory|model|monitor|numdrives|
    numports|numunits|pcb|pchip|serial|spinup|stagger|
    unitstatus|ondegrade(9000S only)
/cx show all where all means attributes and configurations.
/cx show diag
/cx show alarms [reverse]
/cx show rebuild (9000 only)
/cx show verify (9000 only)
/cx show selftest (9000 only)

/cx add type=<RaidType> disk=<p:-p..> [stripe=<Stripe>]
    [noscan] [nocache][group=<3|4|5|6|7|8>] [autoverify]
    [ignoreECC] [name=string (9000 only)]
    [storsave=<protect|balance|perform[quiet]>(9550SX,
    9590SE, 9650SE)] RaidType={raid0, raid1, raid5, raid6
    (9650SE), raid10, raid50, single, spare, JBOD(7000/8000
    only)}
/cx add rebuild=ddd:hh:duration (9000 only)
/cx add verify=ddd:hh:duration (9000 only)
/cx add selftest=ddd:hh (9000 only)

/cx del rebuild=slot_id (9000 only)
/cx del verify=slot_id (9000 only)
/cx del selftest=slot_id (9000 only)

/cx set exportjbod=on|off (9000 only)
/cx set ondegrade=cacheoff|follow (9500S only)
/cx set spinup=mn (9000 only)
/cx set stagger=mn (9000 only)
/cx set autocarve=on|off (9000 only)
/cx set rebuild=enable|disable|<1..5>
    (enable|disable for 9000 only)
/cx set verify=enable|disable|<1..5>
    (enable|disable for 9000 only)
/cx set selftest=enable|disable [task=UDMA|SMART](9000 only)
/cx set autorebuild=on|off (9550SX, 9590SE, and 9650SE only)

/cx update fw=filename_with_path [force] (9000 only)
/cx flush
/cx commit (Windows only) (Also known as shutdown)
/cx start mediascan (7000/8000 only)
/cx stop mediascan (7000/8000 only)
/cx rescan [noscan] NOTE: Does not import non-JBOD on 7/8000
    models.
//localhost>

```

## Help with attributes

As you work with specific objects or commands, you can also use `?` to get help.

For example: If you enter the command `/c0 show` and then need help on what specific attribute syntax is possible, you can use `?` to get help as following:

```
//localhost> /c0 show ?

/cx show
/cx show attribute [attribute ...]   where attribute is:
    achip|allunitstatus|autocarve(9000 series)|
    autorebuild(9550SX only)|bios|carvesize(9000series)|
    driver|drivestatus|exportjbod|firmware|memory|model|
    monitor|numdrives|numports|numunits|ctlbus(9550SX,
    9590SE, 9650SE only)|serial|ondegrade (9000S only)|pcb|
    pchip|spinup|stagger|unitstatus|
/cx show all where all means attributes and configurations.
/cx show diag
/cx show alarms [reverse]
/cx show rebuild                      (9000 only)
/cx show verify                      (9000 only)
/cx show selftest                    (9000 only)
//localhost>
```

## help

This help command provide a table of contents, providing help with the overall navigation of the CLI commands. Typical output looks like the following.

```
//localhost> help
Copyright(c) 2004-2006 Applied Micro Circuits Corporation
(AMCC). All rights reserved.

AMCC/3ware CLI (version 2.x)

Commands   Description
-----
show       Displays information about controller(s), unit(s) and port(s).
flush      Flush write cache data to units in the system.
rescan     Rescan all empty ports for new unit(s) and disk(s).
update     Update controller firmware from an image file
commit     Commit dirty DCB to storage on controller(s).           (Windows only)
/cx        Controller specific commands.
/cx/ux     Unit specific commands.
/cx/px     Port specific commands.
/cx/bbu    BBU specific commands.                                   (9000 only)
/ex        Enclosure specific commands.                       (9550SX, 9590SE, and 9650SE only)
/ex/slotx  Slot specific commands.
/ex/fanx   Fan specific commands.
/ex/tempx  Enclosure Temperature Sensor specific commands.
```

Certain commands are qualified with constraints of controller type/model support. Please consult the `tw_cli` documentation for explanation of the controller-qualifiers.

The controller-qualifiers of the Enclosure commands (`/ex`) also apply to Enclosure Element specific commands (e.g., `/ex/elementx`).

Type `help <command>` to get more details about a particular command. For more detail information see `tw_cli`'s documentation.

## help show

This command provides specific show-related help, illustrating various ways to use the show command. It provides reports on Controllers, Units and Drives. See the section “Shell Object Commands” on page 23 for more information.

## help flush

This command provides specific flush-related help, illustrating various ways to use the flush command. See the section “Shell Object Commands” on page 23 for more information.

## help rescan

This command provides specific rescan related help, illustrating various ways to use the rescan command. See the section “Shell Object Commands” on page 23 for more information.

## help update

This command provides specific update-related help. See “Shell Object Commands” on page 23 for more information.

## help commit

This command provides specific commit related help, illustrating various ways to use the commit command. See the section “Shell Object Commands” on page 23 for more information.

## help focus

This command provides specific focus related help, illustrating various ways to use the focus command. See the section “Shell Object Commands” on page 23 for more information.

## help /cx

This command provides specific controller **/cx** related help, illustrating various commands associated with the controller **/cx**. See the section “Controller Object Commands” on page 29 for more information.

## help /cx/ux

This command provides specific unit **/cx/ux** related help, illustrating various commands to use on a unit **/cx/ux**. See the section “Unit Object Commands” on page 59 for more information.

## help /cx/px

This command provides specific **/cx/px** related help, illustrating various ways to use the **/cx/px** command. See the section “Port Object Commands” on page 77 for more information.

## help /cx/bbu

This command provides specific **/cx/bbu** related help, illustrating various ways to use the **/cx/bbu** command. See the section “BBU Object Commands” on page 82 for more information.

## help /ex

This command provides specific enclosure **/ex** related help, illustrating various commands associated with the enclosure **/ex**. See the section “Enclosure Object Commands” on page 87 for more information.

## help /ex/slotx

This command provides specific slot **/ex/slotx** related help, illustrating various ways to use **/ex/slotx**. See the section “Enclosure Object Commands” on page 87 for more information.

## help /ex/fanx

This command provides specific fan **/ex/fanx** related help, illustrating various ways to use the **/ex/fanx** command. See the section “Enclosure Object Commands” on page 87 for more information.

## help /ex/tempx

This command provides specific temperature sensor **/ex/tempx** related help, illustrating various ways to use the **/ex/tempx** command. See the section “Enclosure Object Commands” on page 87 for more information.

## Command Logging

This feature logs controller commands from both CLI and 3DM2 into a file. You may be asked to supply this logfile to tech support for troubleshooting.

Set the environment variable `TW_CLI_LOG` to ON or OFF to enable or disable logging of controller commands into a log file called `tw_mgmt.log`.

By default, `TW_CLI_LOG` is set to OFF. The command to start command logging varies by operating system.

- For FreeBSD, Redhat and SuSE, (bash, ksh, or sh), enter  
`export TW_CLI_LOG=ON`
- For Linux (chs C-shell), enter  
`setenv TW_CLI_LOG ON`
- For Windows, enter  
`set TW_CLI_LOG=0`

In Linux, and FreeBSD, the log file is in `/var/log` directory.

In Windows, the log file is in the 3DM2 installation directory if 3DM2 is installed in the system. Otherwise, it is in the current user home directory.

## Return Code

While informative messages are written to standard output, error messages are written to standard error. On success, 0 is returned. On failure, 1 is returned.

### To view the return code for Linux:

At the shell command prompt type:

```
echo $?
```

The screen prints either a 0 or a 1, depending on whether the command was successful or not.

For example, if you had a 3ware controller with an ID of 0, you could type this command:

```
tw_cli /c0 show
(c0 information displayed here)
echo $?
0
```

If you type:

```
tw_cli /c7 show
error: (CLI003) specified controller does not exist.
echo $?
1
```

This example fails (returns 1) because there is no controller 7.

**To view the return code for Windows**, in a command window type

```
tw_cli /c0 show
(c0 info displayed here)
if errorlevel 0 echo 0
0
```

```
tw_cli /c7 show
error....
if errorlevel 1 echo 1
1
```

This example fails (returns 1) because there is no controller 7.

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