

Installation Manual GPS RECEIVER GP-310B

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A SAFETY INSTRUCTIONS

A CAUTION

Do not use the equipment for other than its intended purpose.

Improper use of the equipment can result in personal injury or equipment damage.

No one navigation device should ever be solely relied upon for the navigation of a vessel.

Always confirm position against all available aids to navigation, for safety of vessel and crew.

A CAUTION

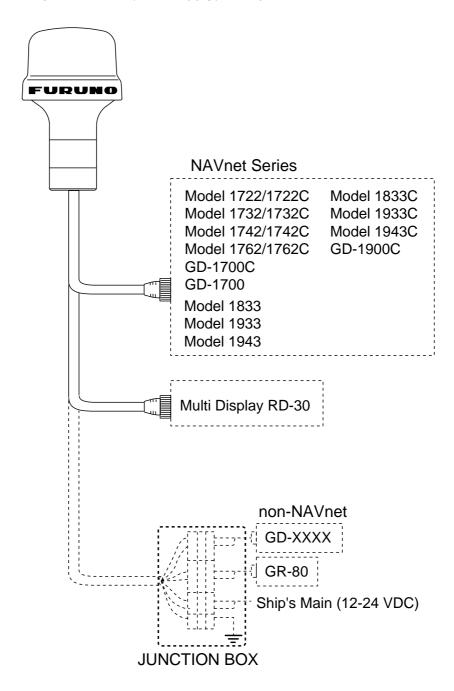
Confirm that the power supply voltage is compatible with the voltage rating of the equipment.

Connection to the wrong power supply can cause fire or equipment damage.

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SYSTEM CONFIGURATION

This antenna incorporates a GPS receiver. It can be connected directly to NAVnet equipment and Multi Display RD-30. However, if it connected to an equipment other than the NAVnet product, a junction box (local supply) is required.



EQUIPMENT LISTS

Standard supply

No.	Name	Туре	Code No.	Qty	Remarks
1	GPS Receiver	GP-310B		1	With 10m cable

Optional equipment

No.	Name	Туре	Code No.	Qty	Remarks
1	Cable Assembly	MJ-A7SPF/SRMD-100	000-144-534	1	10m
2	Mast mounting kit	CP20-0111	004-365-780	1	

1. MOUNTING

Mounting considerations

When selecting a mounting location for the antenna unit keeps in mind the following points.

- The antenna may be mounted three ways: screwed into a pipe (local supply), fixed to a
 post with the optional mast mounting kit, or screwed into an optional mounting base. For
 fixing by the post or pipe, it is recommended to use stays to prevent damage to the GPS
 receiver.
- Select a location out of the radar beam. The radar beam will obstruct or prevent reception of the GPS satellite signal.
- The location should be well away from a VHF antenna. A GPS receiver is interfered by a harmonic wave of a VHF antenna.
- The location should be well away from an Inmarsat-B antenna. Transmission of Inmarsat-B will obstruct or prevent reception of the GPS satellite signal.
- There should be no interfering object within the line-of-sight to the satellites. Objects within line-of-sight to a satellite, for example, a mast may block reception or prolong acquisition time.
- Mount the antenna unit as high as possible. Mounting the antenna unit as high as
 possible keeps it free of interfering objects and water spray, which can interrupt reception
 of GPS satellite signal if the water freezes.
- If the antenna cable is to be passed through a hole which is not large enough to pass the
 connector, you may cut the cable with cutting pliers. Re-connect it after running the cable
 through the hole. Wrap cable with vulcanizing tape and then vinyl tape. Bind the tape end
 with cable-tie.

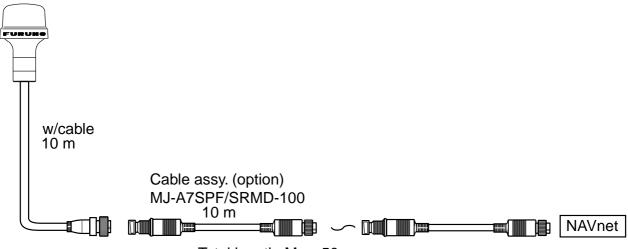
Mounting

Install the antenna unit by referring to installation diagram of page D-1.

2. WIRING

This unit outputs position and speed to external equipment, mainly to NAVnet equipment. To connect to NAVnet equipment, connect waterproof connector directly to NAVnet equipment. For connection to other equipment, use a junction box (local supply), which provides seven terminals. A ten meter cable is attached to this unit. If the distance between this unit and monitor more than 10 m, use optional extension cable (10 m). Up to four extension cables can be connected serially.

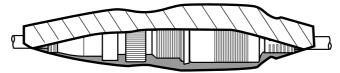
Connecting to FURUNO NAVnet equipment



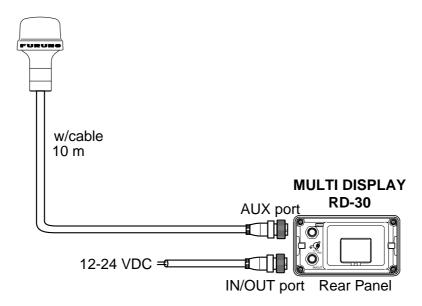
Total length: Max. 50 m

Waterproofing connector

If you use the optional extension cable(s), wrap connector(s) with vulcanizing tape and then vinyl tape for waterproofing. Bind the tape end with cable-tie.

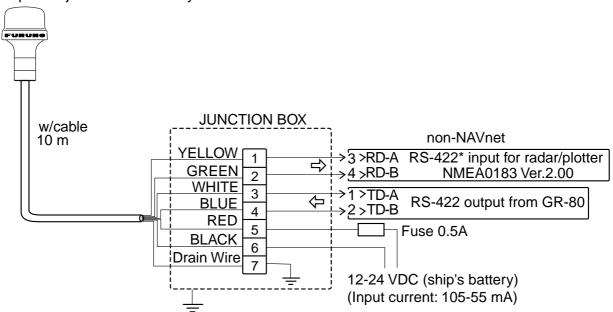


Connecting to FURUNO Multi Display RD-30



Connecting to other type of equipment

Cut the connector and fabricate the cable end, using a crimp-on lug similar terminal. Prepare a junction box locally.



*: RS-422 output can be received by current loop.

- **Note1)** Maximum input voltage is 31.2 VDC. Voltage higher than that will damage the antenna. To connect battery of over 31.2 VDC, contact your dealer to request connection of external circuit.
- Note2) When connecting a FURUNO external DGPS beacon receiver (such as the GR-80) to this unit, set the external DGPS beacon receiver as follows:

 Byte Format, 8-6; First Bit, LSB; Parity Bit, None; Stop Bit, 1; Bit Rate, 8.
- **Note3)** The signal ground and frame ground are separated, however the power line is not isolated. Therefore, do not connect the signal ground to the frame ground when connecting other equipment to a positive ground battery.

Output/Input data format

Priority	ority Input data		Output da	Output data		Default
					of Output	
					Cycle	
High			GPDTM	Geometric datum	Yes	Yes
1	XXGGA	Position	GPGGA	GPS fix data	Yes	Yes
	XXZDA	UTC date	GPZDA	UTC time and date	Yes	Yes
	XXGLL	Position	GPGLL	Geographic	Yes	
				position		
			GPGSA	Fixing state, DOP	Yes	
			GPGSV	Satellite	Yes	Yes
				information		
			GPVTG	Course over	Yes	Yes
				ground and ground		
				speed		
	XXRMC	Position, UTC	GPRMC	Recommended	Yes	
		date		minimum specific		
↓				GPS/TRANSIT		
Low				data		

- Note1) Data output in order from high to low priority.
- Note2) GPDTM data is attached in front of GPGGA, GPGLL and GPRMC when each of those sentences is output.
- Note3) XX means talker not specified.

3. DEFAULT SETTINGS

	Setting	Default setting
GPS data	Initial Latitude/Longitude	North=34'44.0000, East=135'21.0000
	UTC Time	1997/1/1 0:0:12
	Antenna Height	0 m
	Almanac Data	_
	Almanac Date	1980/1/6 0:0:0
	Ephemeris Data	_
Receiver	Local Zone Time	+0
parameter	PDOP	6
	Geometric Datum	1(WGS84)
	MASK Elevation	5°
	Disable satellite	0000000(none)
	Smoothing	2 (Standard)
	Dynamic	2 (Standard)
	Data Output Cycle	DTM, GGA, ZDA, GSV, VTG (1s)
	DGPS Setting Parameter	1 (LSB first)

Note) For connecting to equipment other than a NAVnet product, the monitor displays the latitude and longitude of Nishinomiya, Japan as initial position for about 90 seconds after the power is turned on. This is because no back up is provided when connecting to non-NAVnet equipment.

SPECIFICATIONS OF THE BLACKBOX GPS SENSOR GP-310B

1 GENERAL

1.1 Receiving Channels 12 channels parallel, 12 satellite tracking

1.2 Rx Frequency 1575.42 MHz

1.3 Rx Code C/A code

1.4 Position Fixing System All in view, 8-state Kalman filter

1.5 Position Accuracy

GPS: 10 m approx., 95% of the time (HDOP 4)

DGPS: 5 m approx., 95% of the time

1.6 Tracking Velocity 999 kt

1.7 Position-fixing Time Warm start: 12 s, Cold start: 90 s

1.8 Position Update Interval 1 s

2 I/O INTERFACE

2.1 Data format IEC 61162-1 (NMEA 0183 Ver.2.30)

2.2 Output data GGA, ZDA, GSV, VTG2.3 Input data DGPS: RTCM SC-104

Control command

3 POWER SUPPLY

3.1 Antenna Unit 12-24 VDC: 70-40 mA

4 ENVIRONMENTAL CONDITION

4.1 Ambient Temperature -25°C to +70°C

4.2 Relative Humidity 95% at 40°C

4.3 Water proofing IPX6

4.4 Vibration IEC 60945

5 COATING COLOR

5.1 Antenna Unit N9.5

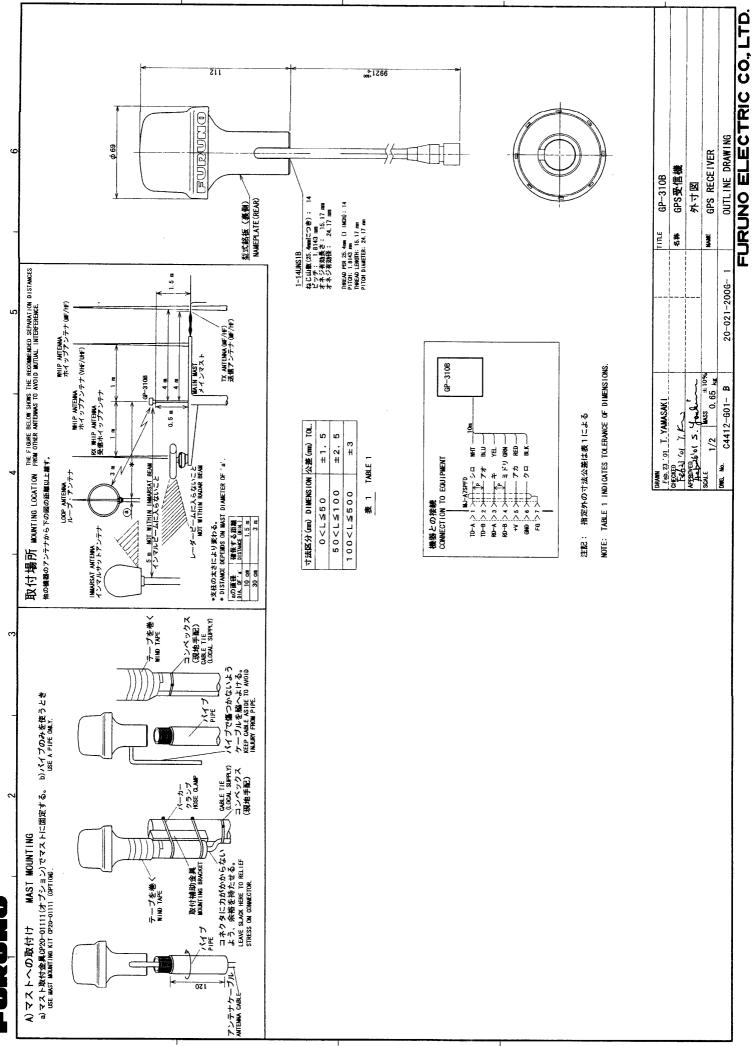
PACKING LIST

20AU-X-9851 -1 1/1

GP-310B (E)

NAME	OUTLINE	DESCRIPTION/CODE No.	Q' TY
ユニット UN	T		
GPS 受信機 GPS RECEIVER	φ 69 Φ	GP-310B-E	1
		000-144-512	





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(TENI) GP-310B

Your Local Agent/Dealer

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